# Processes and Threads

DS 5110: Big Data Systems Spring 2025 Lecture 3

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Some material taken/derived from:

• Wisconsin CS 544 by Tyler Caraza-Harter.

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### Learning objectives

- Describe the interaction between schedulers, CPUs, processes vs. threads, and address spaces
- Understand various basic CPU scheduling policies: FIFO, SJF (STCF), RR
  - And their pros and cons
- Use Linux commands to track running programs and manipulate the scheduling behaviors of them

### Motivation

- Modern CPUs have many cores (maybe dozens)
- Trend: more cores rather than faster cores
- **Problem:** a simple Python program can use at most ONE core
  - Less if it accesses files or the Internet
- Understanding processes and threads will:
  - Let us write programs that fully utilize CPU resources
  - Decide the structure of our concurrent program (processes or threads) depending on the situation

# Outline

- Virtual address spaces
- Processes vs. Threads
- CPU scheduling policies
- Demos

#### **Processes and address spaces**

- Address spaces
  - A process is a running program
  - Each process has its own virtual address space
  - The same virtual address generally refers to different memory in different processes
  - Regular processes cannot directly access physical memory or other addr spaces



#### **Processes and address spaces**

- Address spaces
  - A process is a running program
  - Each process has its own virtual address space
  - The same virtual address generally refers to different memory in different processes
  - Regular processes cannot directly access physical memory or other addr spaces
  - Address spaces can have holes (N is typically much bigger than M)
  - Physical memory for a process need not be contiguous





https://pythontutor.com













- CPUs
  - CPUs are attached to at most one instruction pointer at any given time
  - They run code by executing instructions and advancing the instruction pointer
  - **Note:** interpreter left out for simplicity (CPU points to interpreter code, which points to Python bytecode)



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#### Threads

Threads have their own instruction pointers and stacks, but share heap



Multi-threaded process:



## **CPU** scheduling

- CPU scheduling
  - CPU scheduler is an important sub system in an operating system
  - A scheduler decides when to run which threads
  - Context switch: change which thread a CPU is running



#### Scheduling restrictions: blocked threads

- Threads can be in one of three states
  - Running: CPU is executing it
  - **Blocked:** waiting on something other than CPU (network, input, disk, etc.)
  - **Ready:** scheduler can choose to run it



### **CPU scheduling policies**

- Threads get queued up and the CPU scheduler will select one from the ready queue for execution
- The scheduling policies may have tremendous effects on the system efficiency

#### First-In, First-Out

#### Workload assumptions

- 1. Each job runs for the same amount of time
- 2. All jobs arrive at the same time
- 3. All jobs only use the CPU (no I/O)
- 4. The runtime of each job is known

#### FIFO

• First-In, First-Out: Run jobs in arrival order

Proc	Arrival time	Runtime
P1	~0	5
P2	~0	5
P3	~0	5

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	Proc	Α	rrival time		Runtime		
	P1		~0		5		
	P2		~0		5		
	P3		~0		5		
Gantt chart	P <sub>1</sub>		P <sub>2</sub>		P <sub>3</sub>		
0		5		1	0	1	5

#### FIFO

• First-In, First-Out: Run jobs in arrival order



What is the average turnaround time? Def: turnaround\_time = completion\_time - arrival\_time

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### Example: big first job

Proc	Arrival time	Runtime
P1	~0	80
P2	~0	5
P3	~0	5

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Proc	Arrival time	Runtime
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P2	~0	5
P3	~0	5

What is the average turnaround time?



Average turnaround time: (80+85+90) / 3 = 85

# Convoy effect!!



#### **Better schedule?**



#### **Shortest Job First (SJF)**

#### Passing the tractor

- New scheduler: SJF (Shortest Job First)
- Policy: When deciding which job to run, choose the one with the smallest runtime

#### **Example: SJF**

Proc	Arrival time	Runtime
P1	~0	80
P2	~0	5
P3	~0	5

#### What is the average turnaround time with SJF?

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Proc	Arrival time	Runtime
P1	~0	80
P2	~0	5
P3	~0	5

#### What is the average turnaround time with SJF?



Average turnaround time: (5+10+90) / 3 = 35

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#### Workload assumptions

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-2. All jobs arrive at the same time-

3. All jobs only use the CPU (no I/O)

4. The runtime of each job is known

#### What if jobs arrive at different time?

### **Shortest Job First (arrival time)**

Proc	Arrival time	Runtime
P1	~0	80
P2	~15	20
P3	~15	10

#### What is the average turnaround time with SJF?

### Shortest Job First (arrival time)

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P1	~0	80
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What is the average turnaround time with SJF?



### Shortest Job First (arrival time)

Proc	Arrival time	Runtime
P1	~0	80
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P3	~15	10

What is the average turnaround time with SJF?



Average turnaround time: (80+75+95) / 3 = -83.3

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#### A preemptive scheduler

- Previous schedulers: FIFO and SJF are nonpreemptive
- New scheduler: STCF (Shortest Time-to-Completion First)
- Policy: Switch jobs so we always run the one that will complete the quickest

Proc	Arrival time	Runtime
P1	~0	80
P2	~15	20
P3	~15	10



SJF



What is the average turnaround time with STCF?



Average turnaround time: (110+30+10) / 3 = 50

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# What if jobs do I/Os as well?

- No good if a program can only do pure CPUintensive compute
- A common execution pattern of the typical big data applications (Hadoop, Spark, Dask)
  - Completes the CPU burst, performs I/O (e.g., read more CSV files from disk into DRAM), rejoins the ready queue and completes the second CPU bursts...

#### Not I/O Aware



#### Poor use of resources

Not I/O Aware



#### Poor use of resources

# I/O Aware (Overlap)



Overlap allows better use of resources!

# Round Robin (RR)

Process	Burst time
А	~5
В	~5
С	~5

 Each process gets a small unit of CPU time (time slice). After this time has elapsed, the process is preempted and added to the end of the ready queue

• SJF



Time

• **RR** (time slice = 1)

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#### Demos ...