

# Google File System

*DS 5110: Big Data Systems (Spring 2023)*

Lecture 3a

Yue Cheng



# Google file system (GFS)

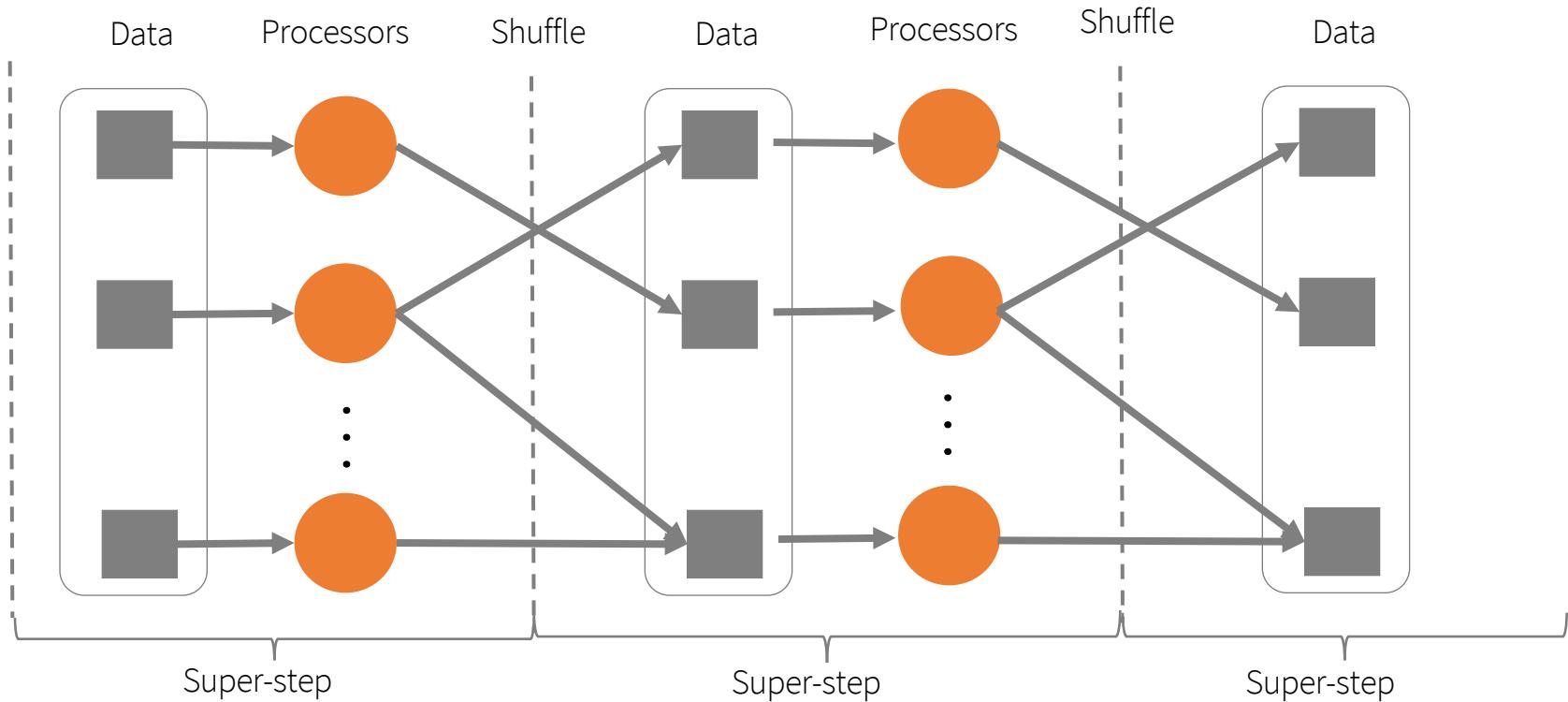
- Goal: a global (distributed) file system that stores data across many machines
  - Need to handle 100's TBs
- Google published details in 2003
- Open source implementation:
  - Hadoop Distributed File System (HDFS)



# Workload-driven design

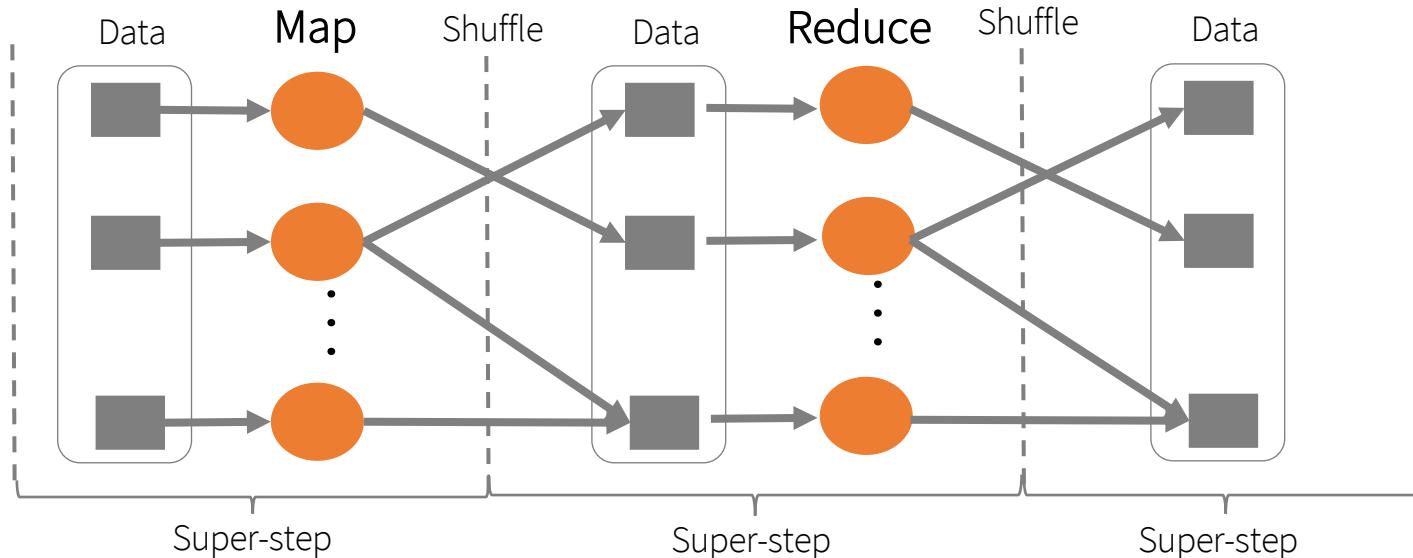
- MapReduce workload characteristics
  - Huge files (GBs)
  - Almost all writes are appends
  - Concurrent appends common
  - High throughput is valuable
  - Low latency is not

# Example workloads: Bulk Synchronous Processing (BSP)



\*Leslie G. Valiant, A bridging model for parallel computation, Communications of the ACM, Volume 33 Issue 8, Aug. 1990

# MapReduce as a BSP system

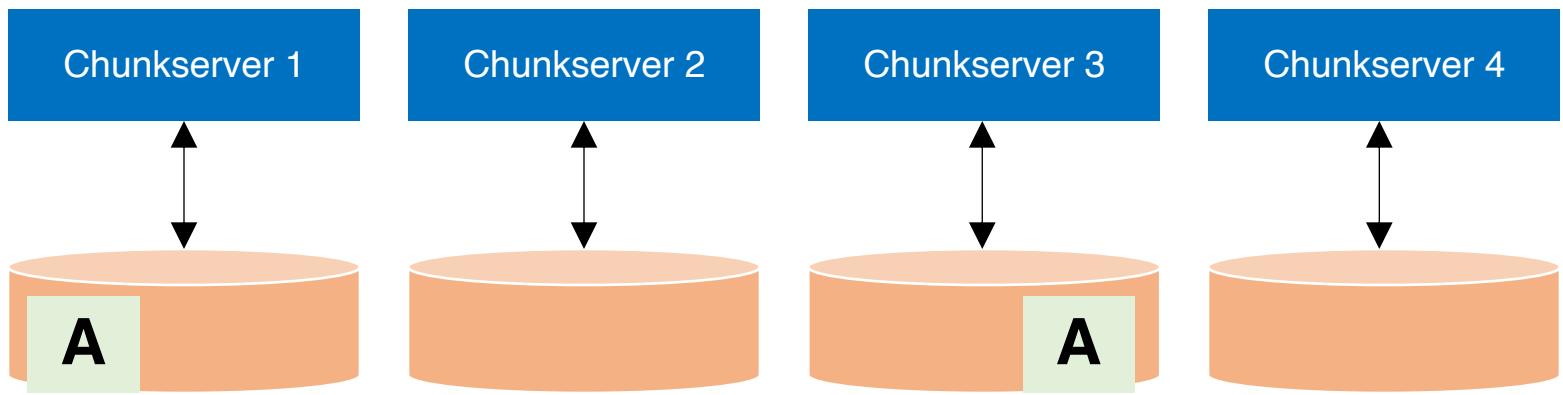


- Read entire dataset, do computation over it
  - Batch processing
- Producer/consumer: many producers append work to file concurrently; one consumer reads and does work

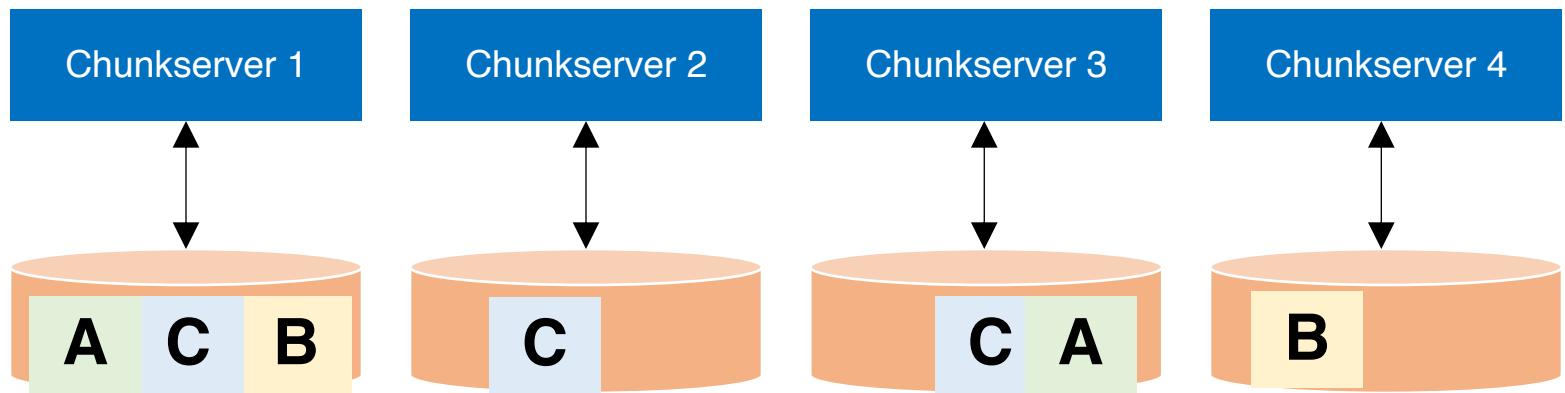
# Workload-driven design

- Build a global (distributed) file system that incorporates all these application properties
- Only supports **features required by applications**
- Avoid difficult local file system features, e.g.:
  - links

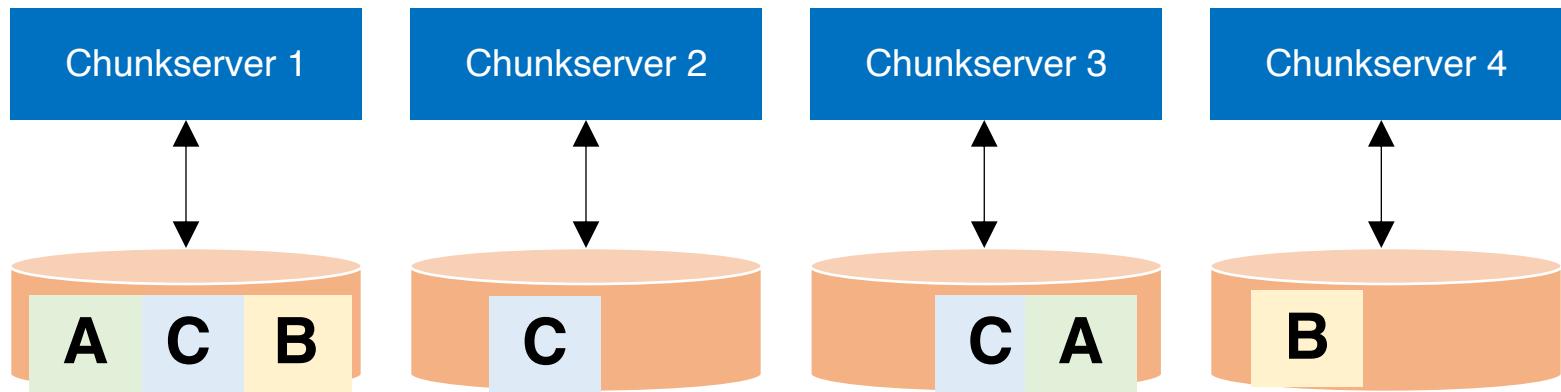
# Replication



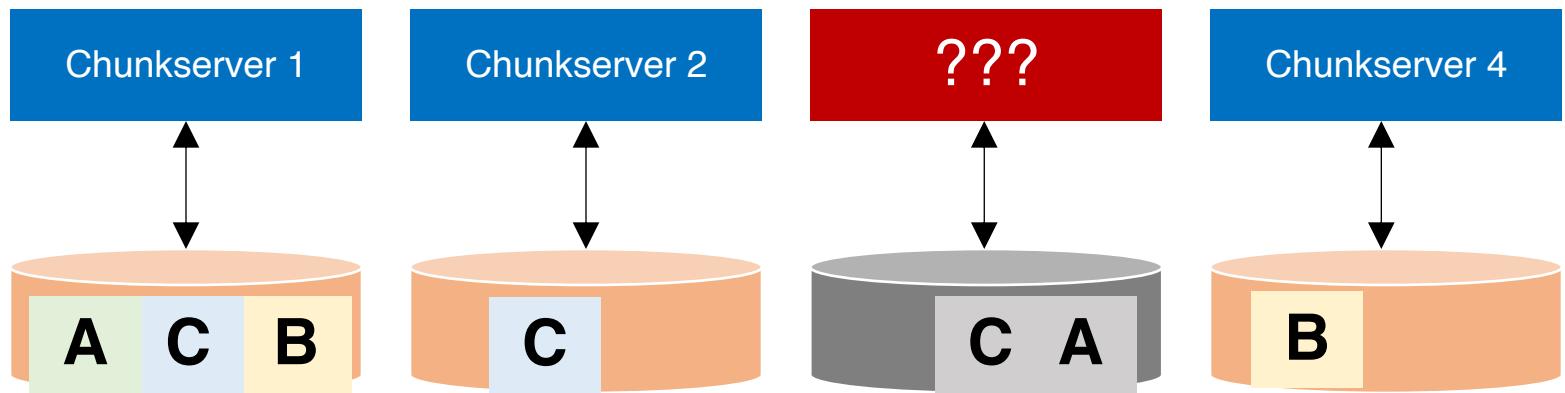
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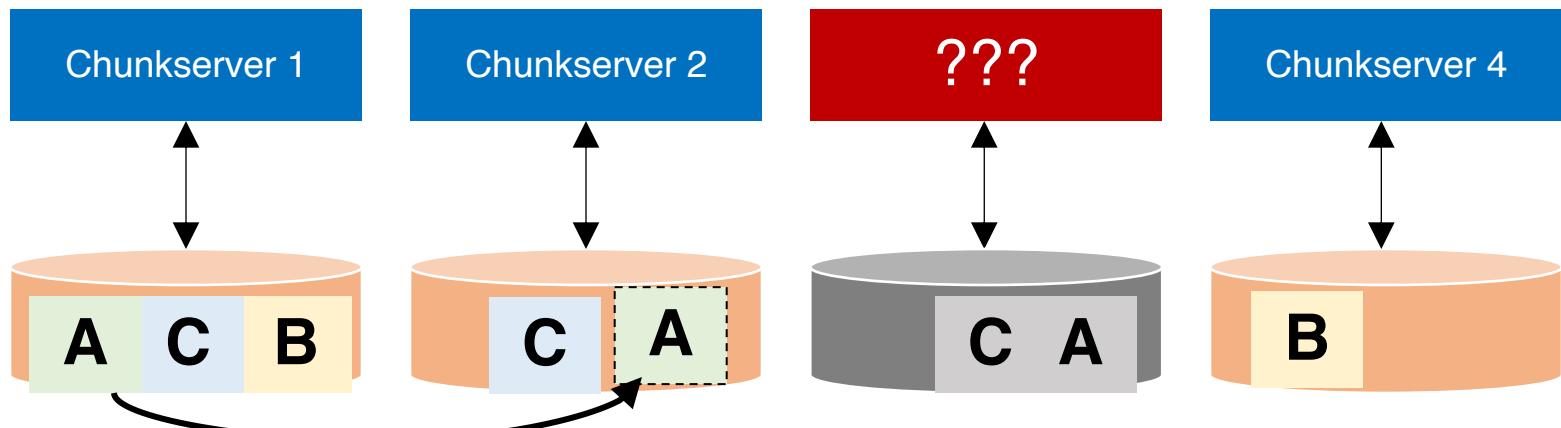
# Resilience against failures



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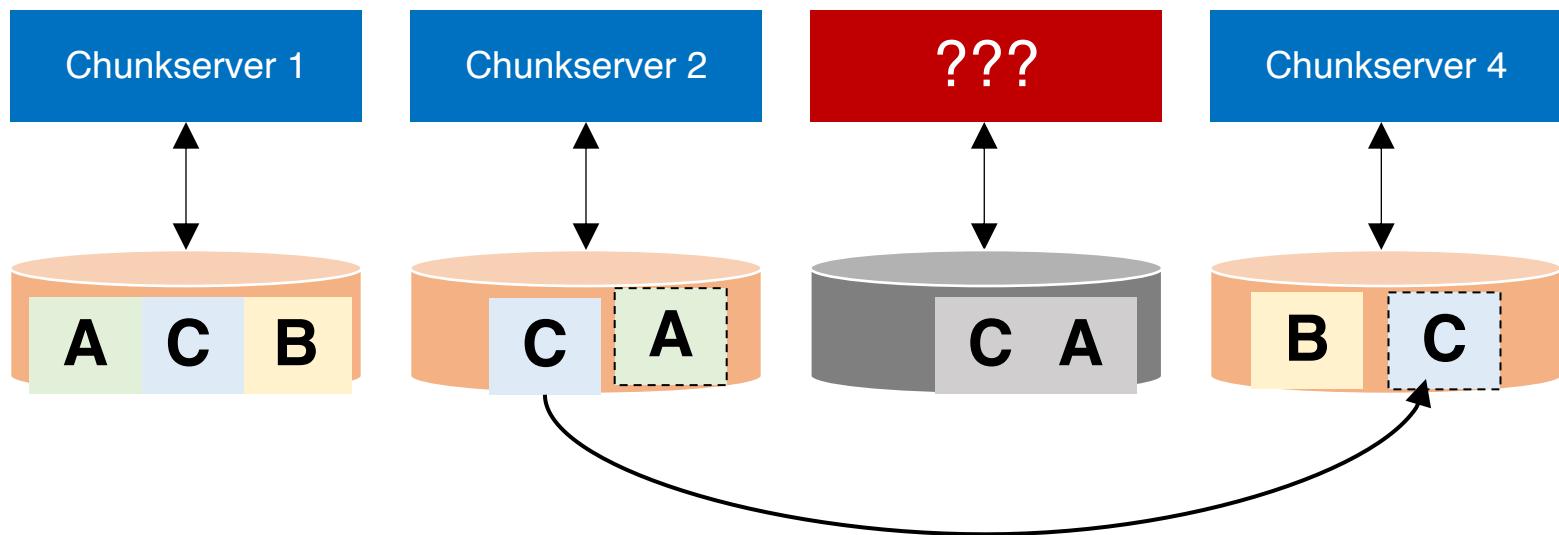


# Data recovery



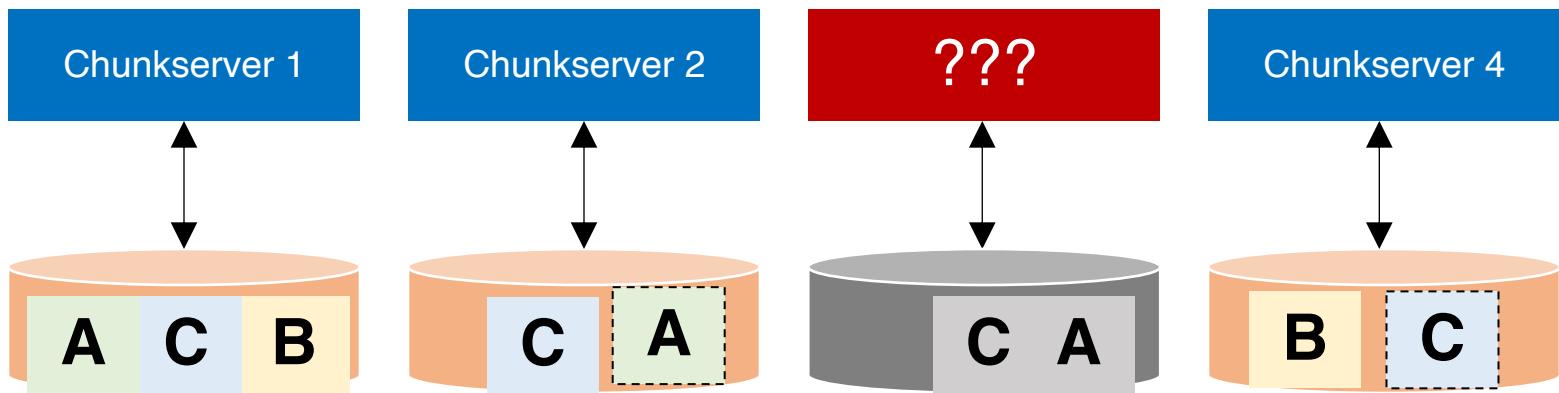
Replicating A to maintain a replication factor of 2

# Data recovery



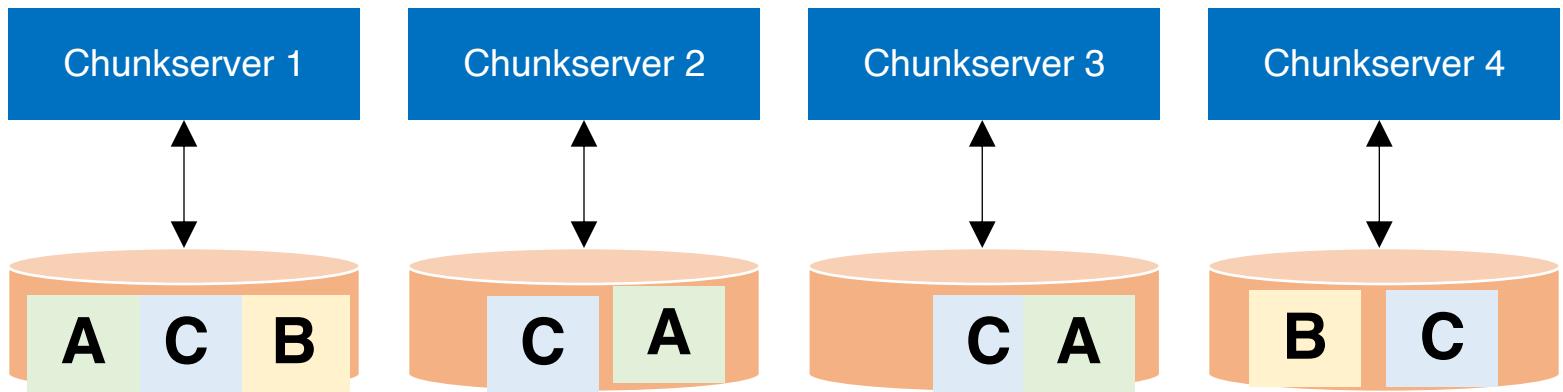
Replicating C to maintain a replication factor of 3

# Data recovery



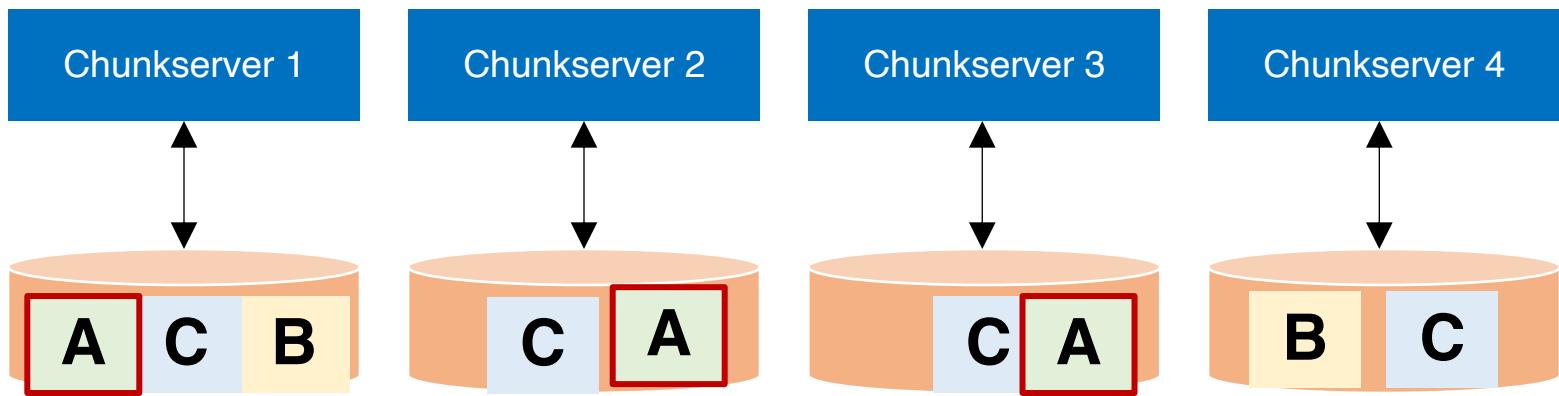
Machine may be dead forever, or it may come back

# Data recovery

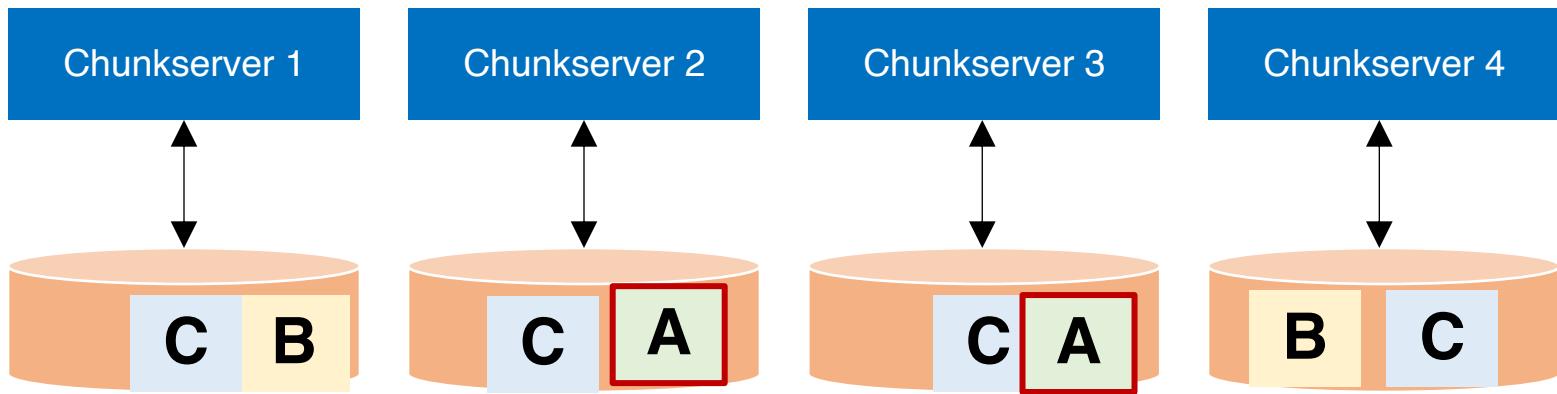


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# Data recovery



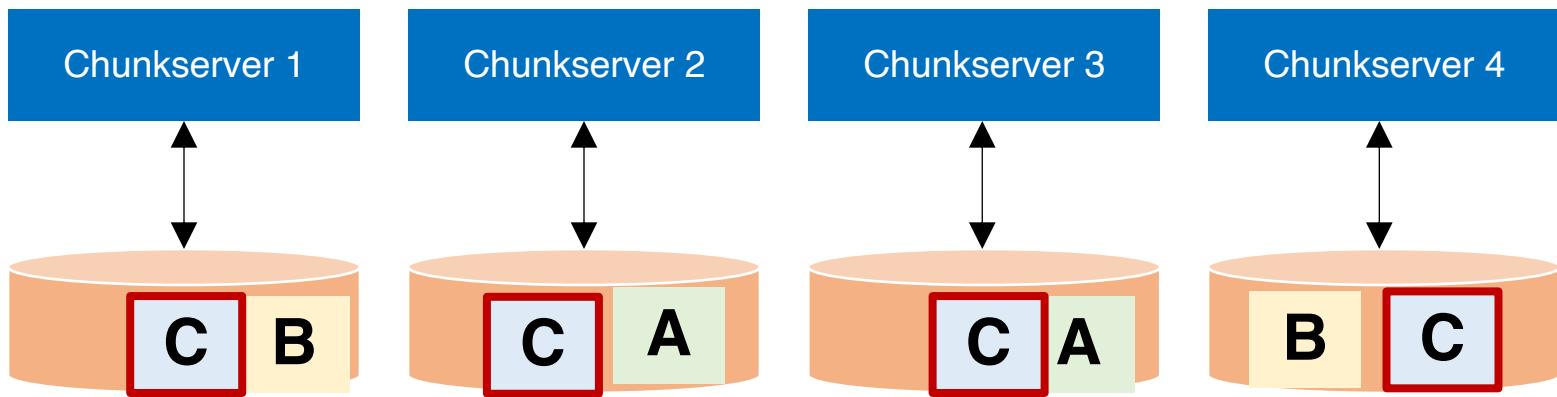
# Data recovery



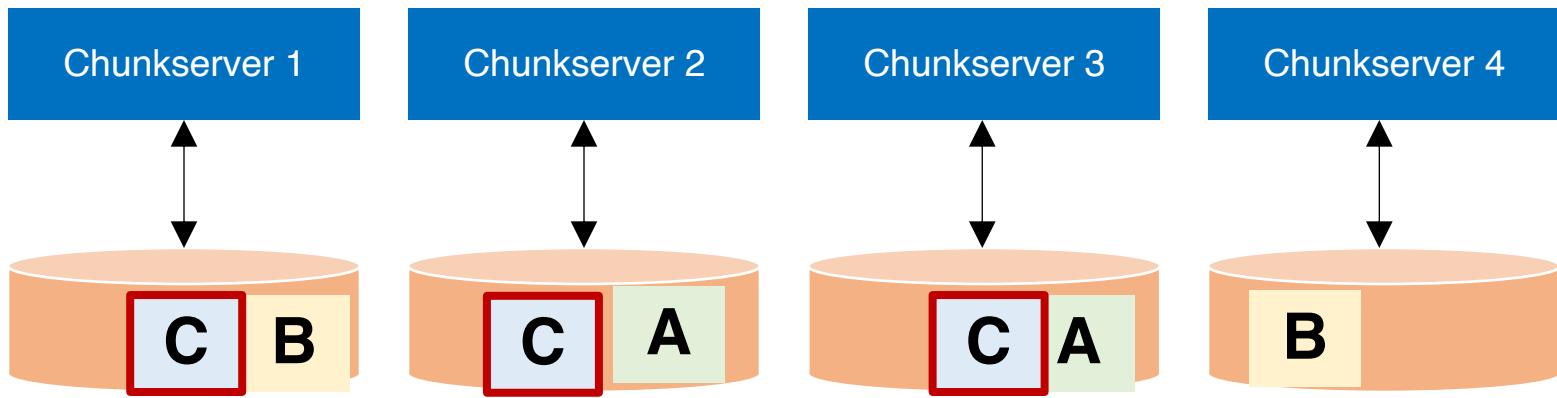
## Data Rebalancing

Deleting one A to maintain a replication factor of 2

# Data recovery



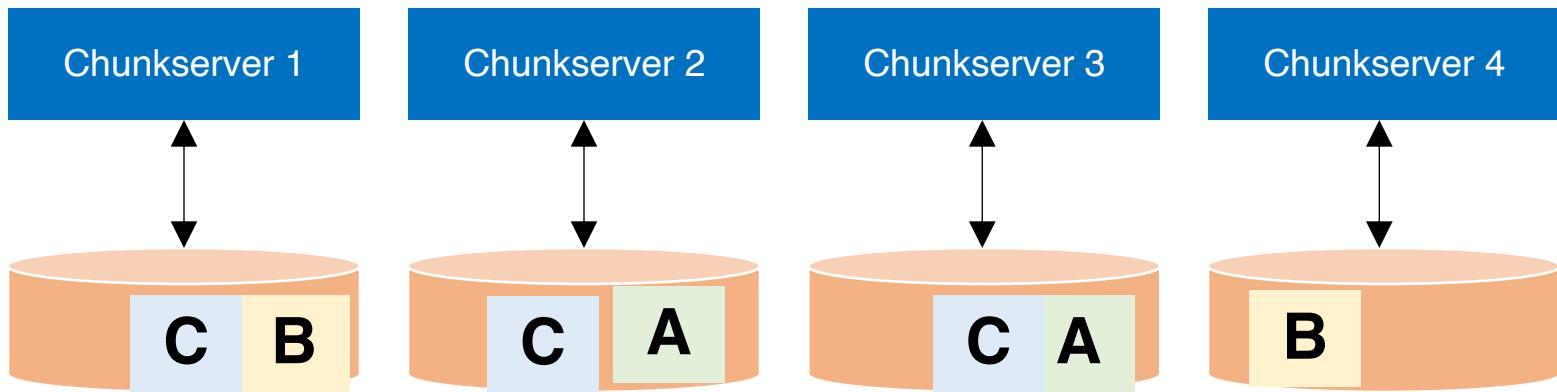
# Data recovery



## Data Rebalancing

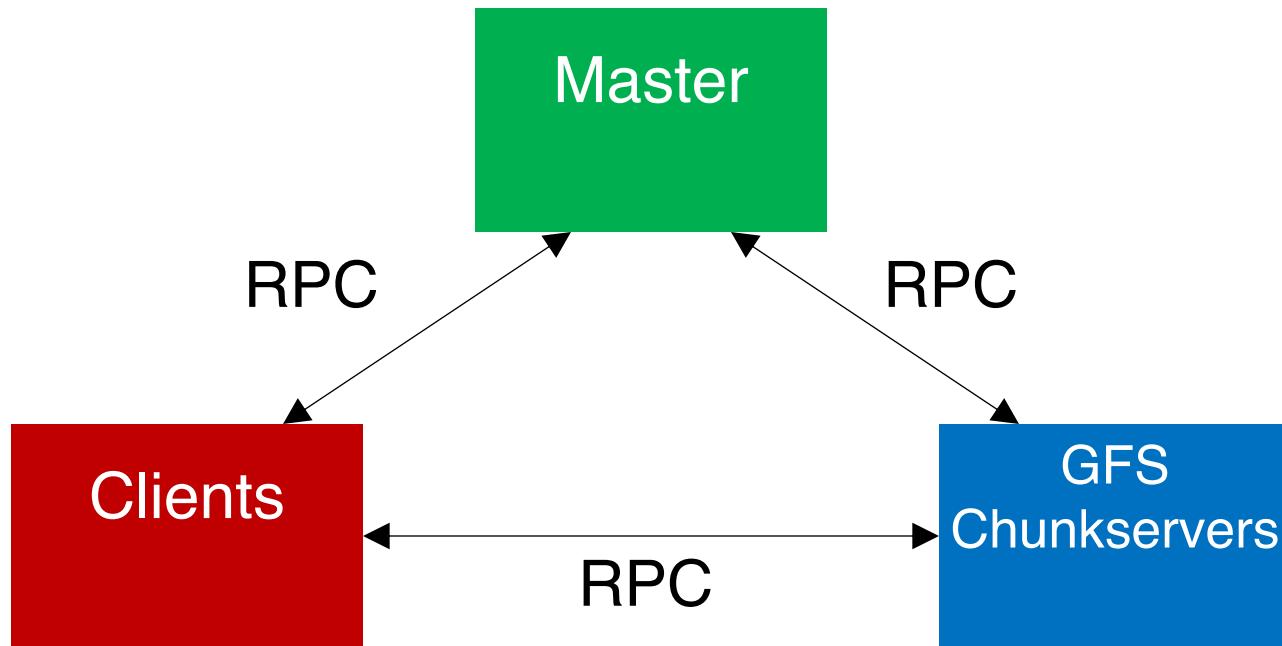
Deleting one C to maintain a replication factor of 3

# Data recovery

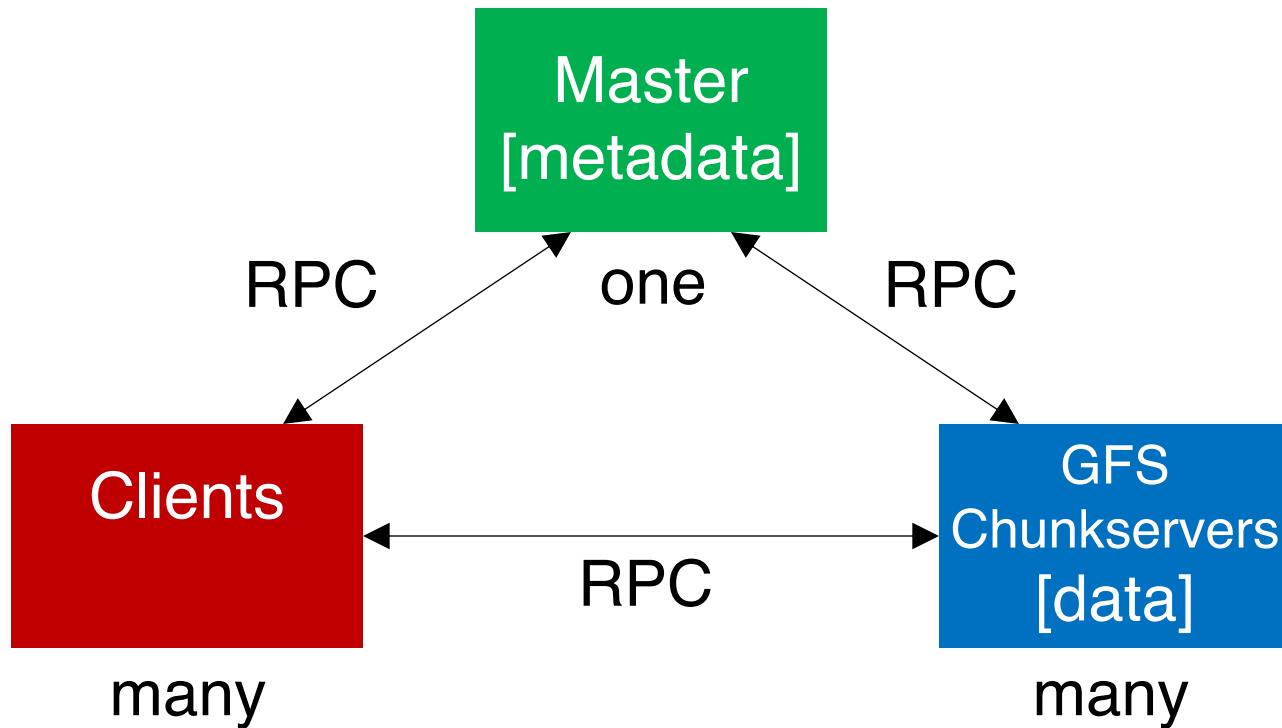


**Question:** how to maintain a global view of all data distributed across machines?

# GFS architecture: logical view



# GFS architecture: logical view



# BTW, what is RPC?

RPC = Remote procedure call

# Motivation: Why RPC?

- The typical programmer is trained to write single-threaded code that runs in one place
- **Goal:** Easy-to-program network communication that makes client-server communication **transparent**
  - Retains the “feel” of writing centralized code
    - Programmer needn’t think about the network
    - Avoid tedious socket programming

# What's the goal of RPC?

- Within a single program, running in a single process, recall the well-known notion of a **procedure call**:
  - **Caller** pushes arguments onto stack,
    - jumps to address of **callee** function
  - **Callee** reads arguments from stack,
    - executes, puts return value in register,
    - returns to next instruction in caller

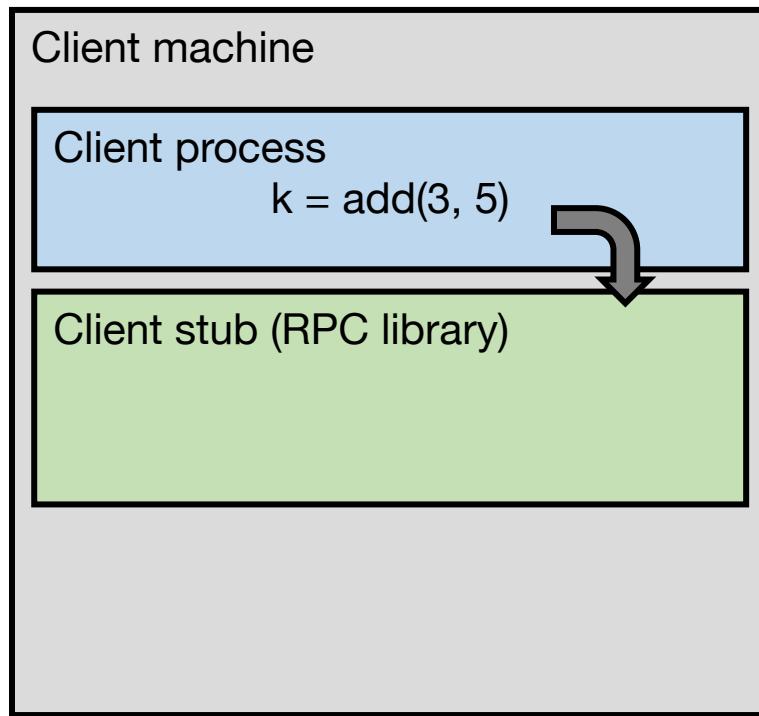
# What's the goal of RPC?

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**RPC's Goal:** make communication appear like a local procedure call: transparency for procedure calls – way less painful than sockets...

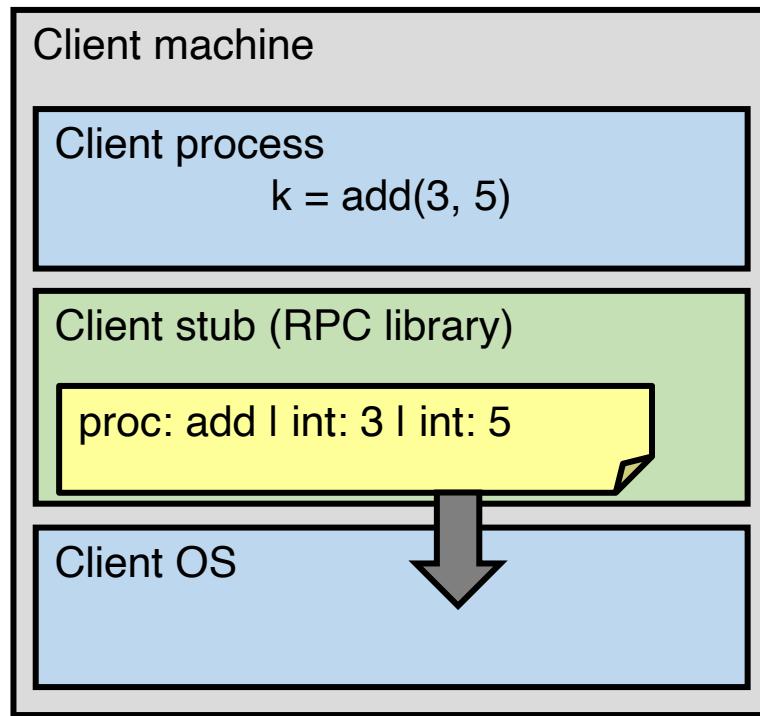
# A day in the life of an RPC

1. Client calls stub function (pushes parameters onto stack)



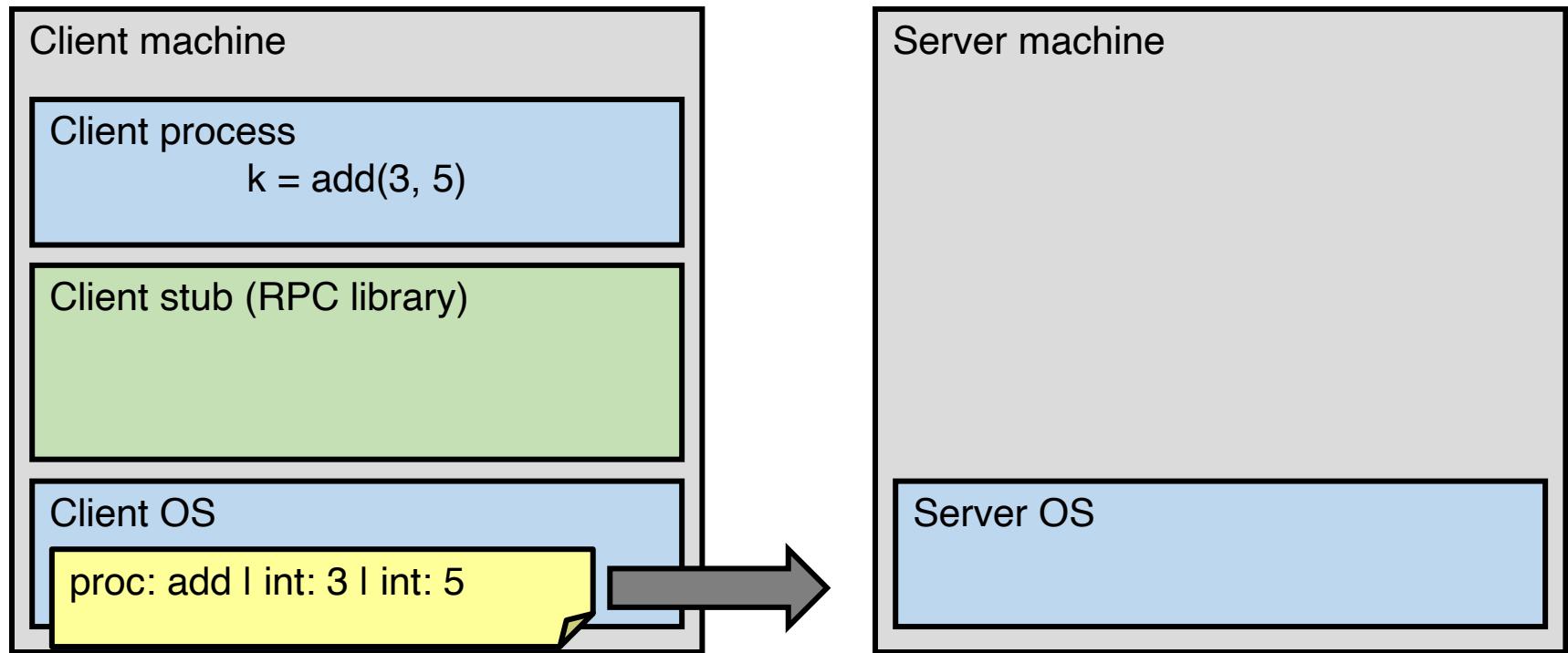
# A day in the life of an RPC

1. Client calls stub function (pushes parameters onto stack)
2. Stub marshals parameters to a network message



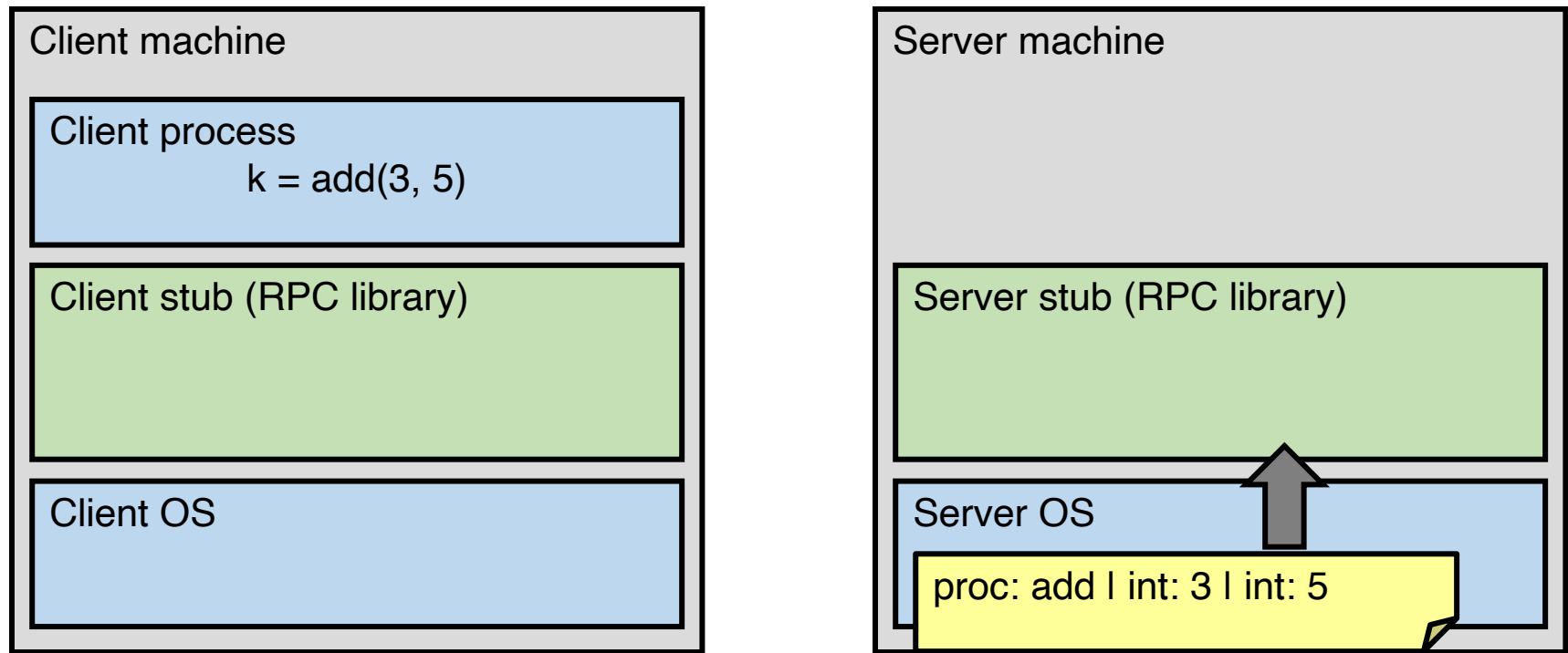
# A day in the life of an RPC

2. Stub marshals parameters to a network message
3. OS sends a network message to the server



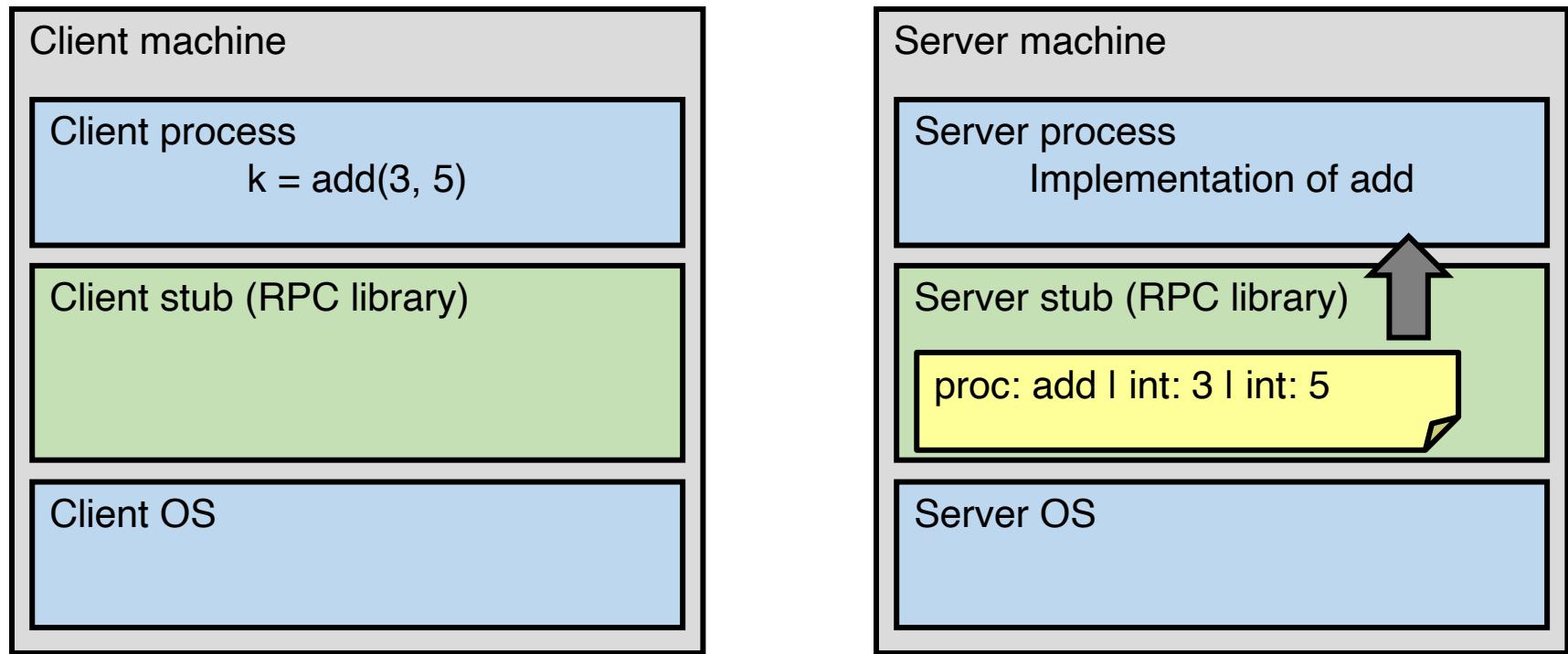
# A day in the life of an RPC

3. OS sends a network message to the server
4. Server OS receives message, sends it up to stub



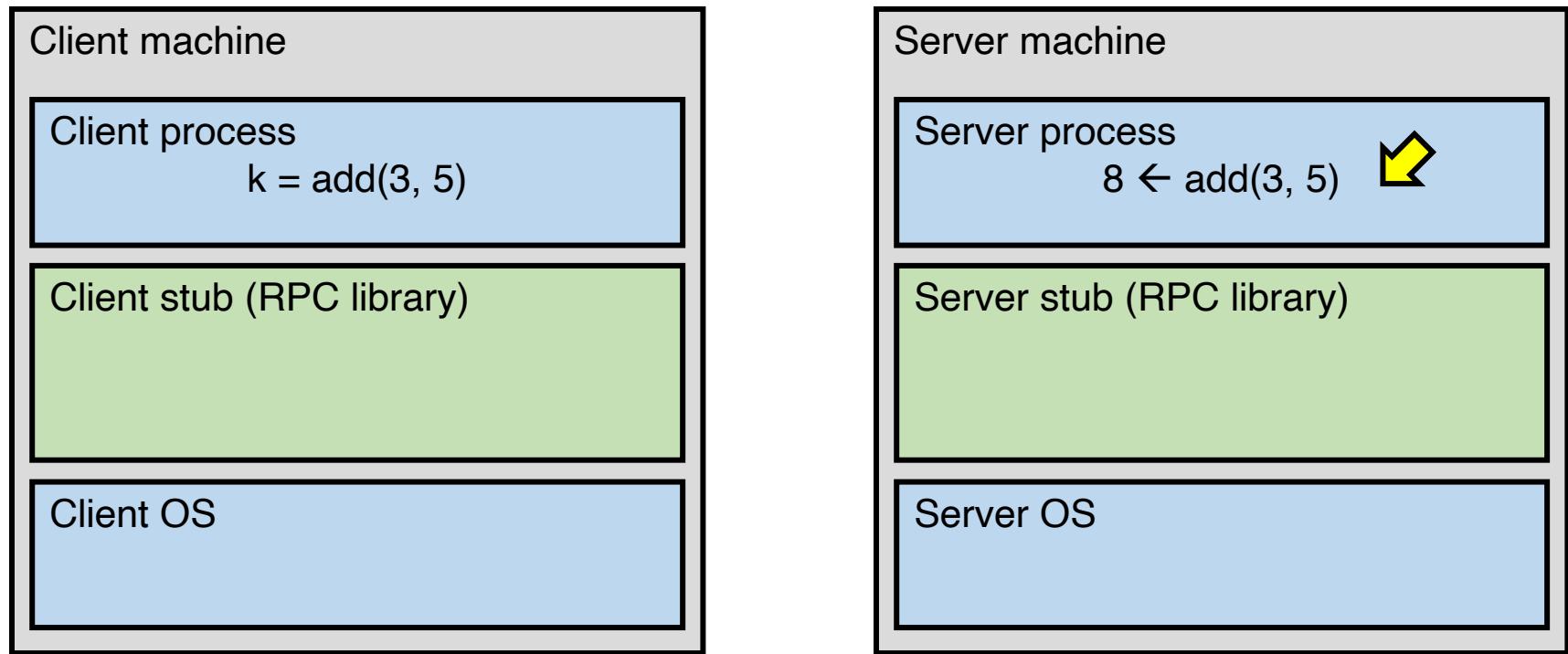
# A day in the life of an RPC

4. Server OS receives message, sends it up to stub
5. Server stub unmarshals params, calls server function



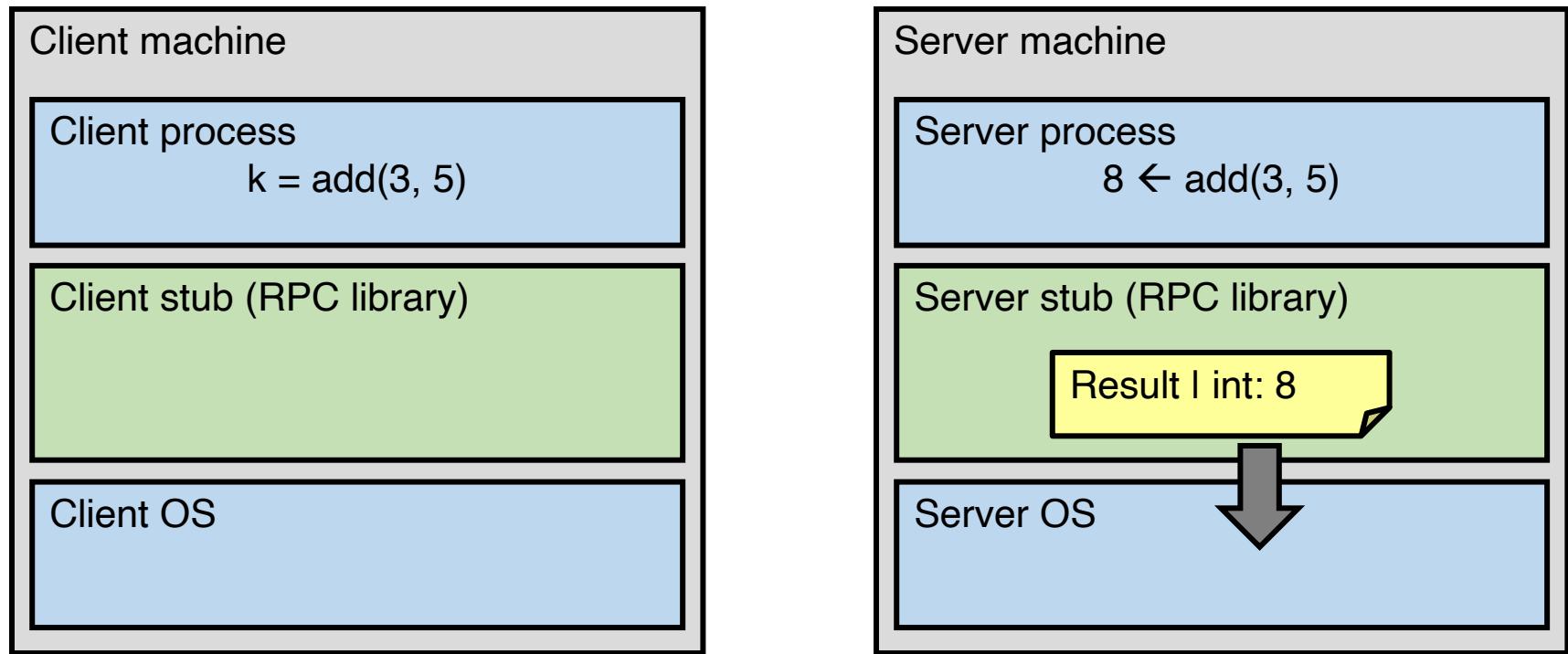
# A day in the life of an RPC

5. Server stub unmarshals params, calls server function
6. Server function runs, returns a value



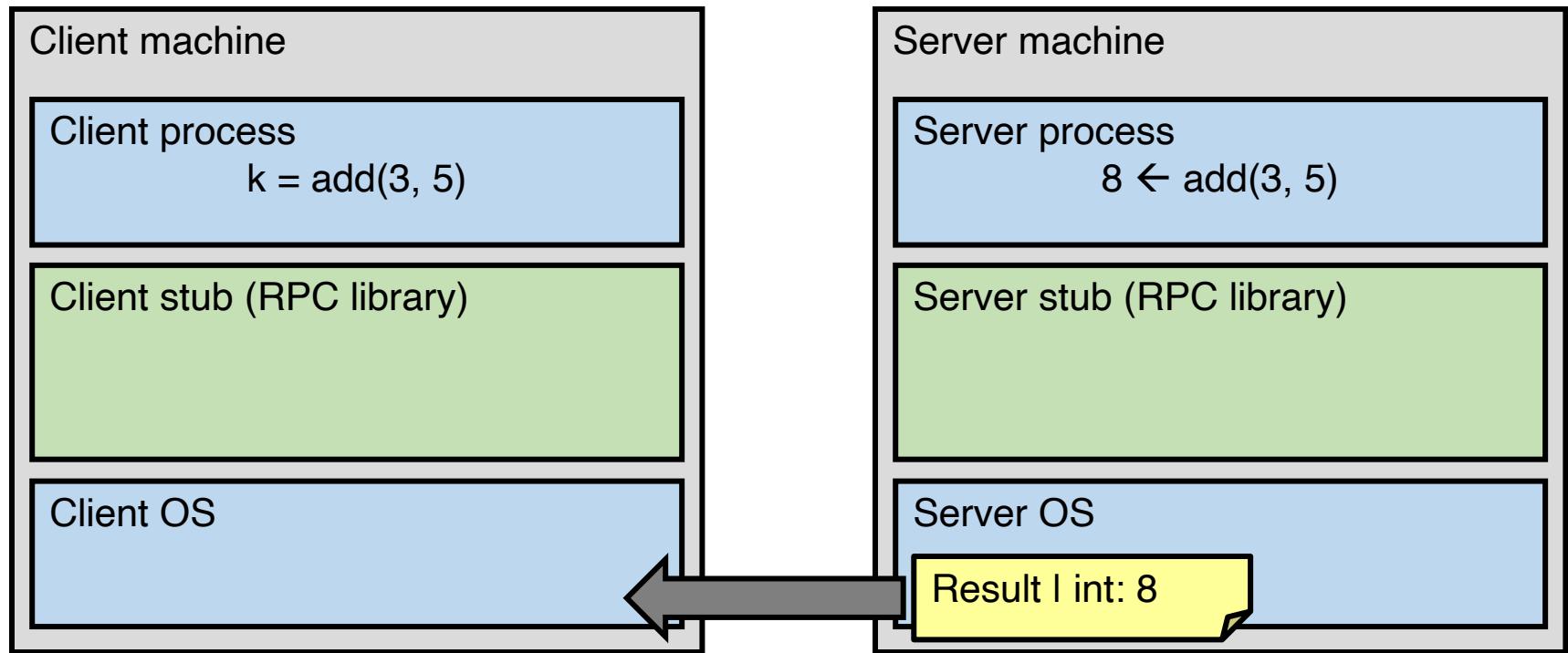
# A day in the life of an RPC

6. Server function runs, returns a value
7. Server stub marshals the return value, sends message



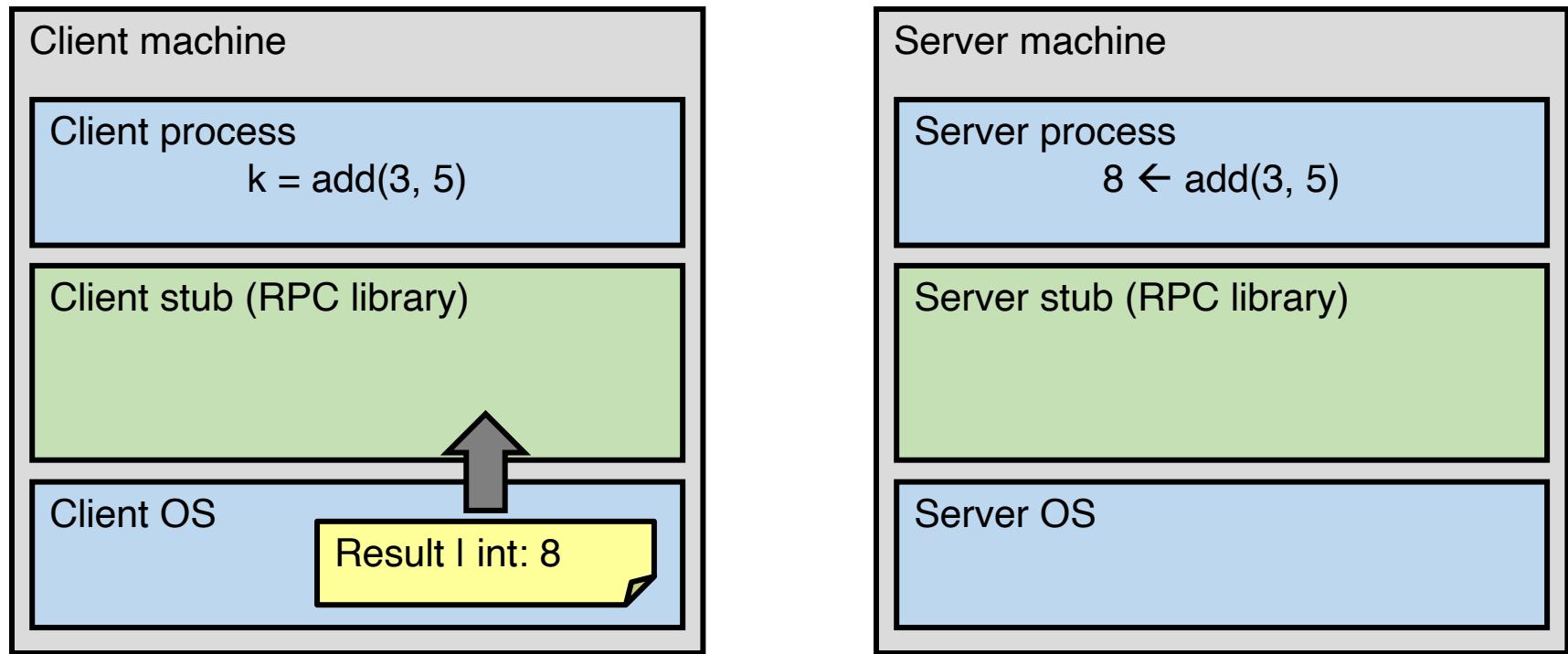
# A day in the life of an RPC

7. Server stub marshals the return value, sends message
8. Server OS sends the reply back across the network



# A day in the life of an RPC

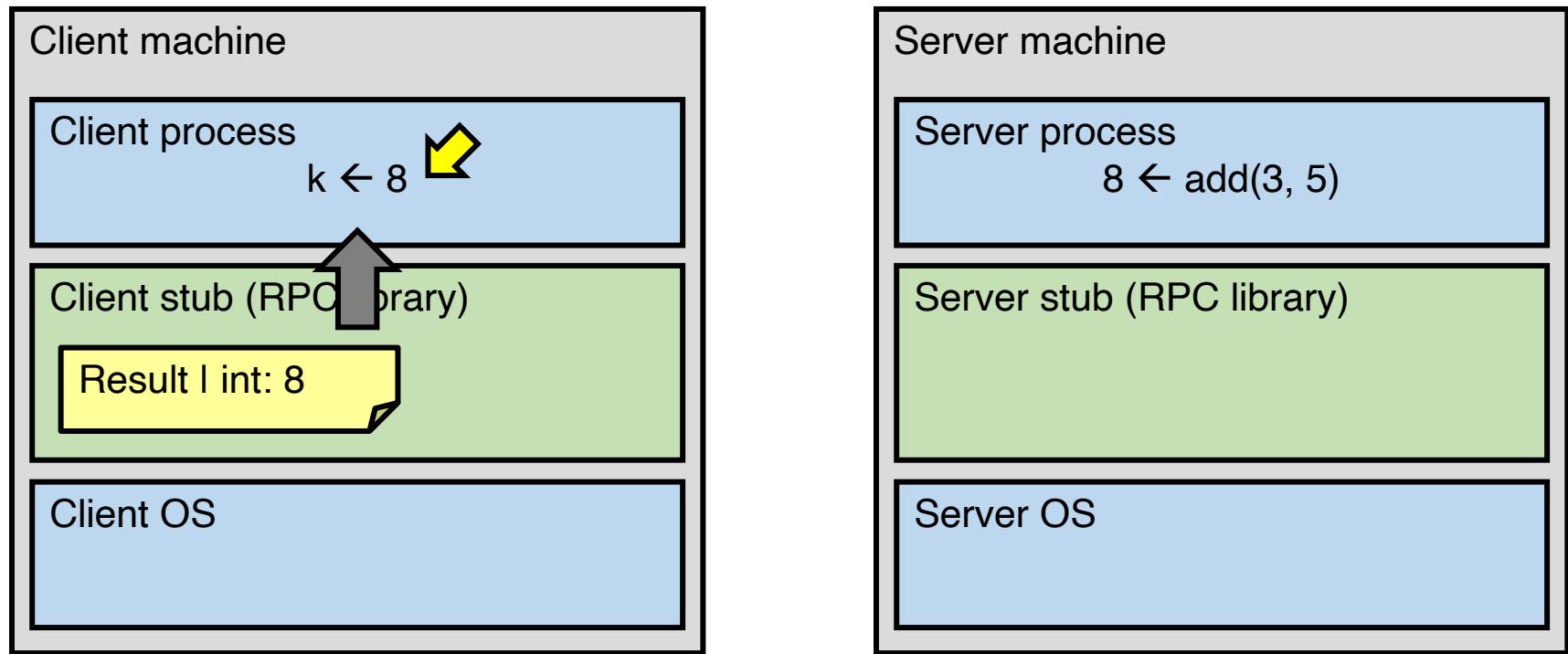
8. Server OS sends the reply back across the network
9. Client OS receives the reply and passes up to stub



# A day in the life of an RPC

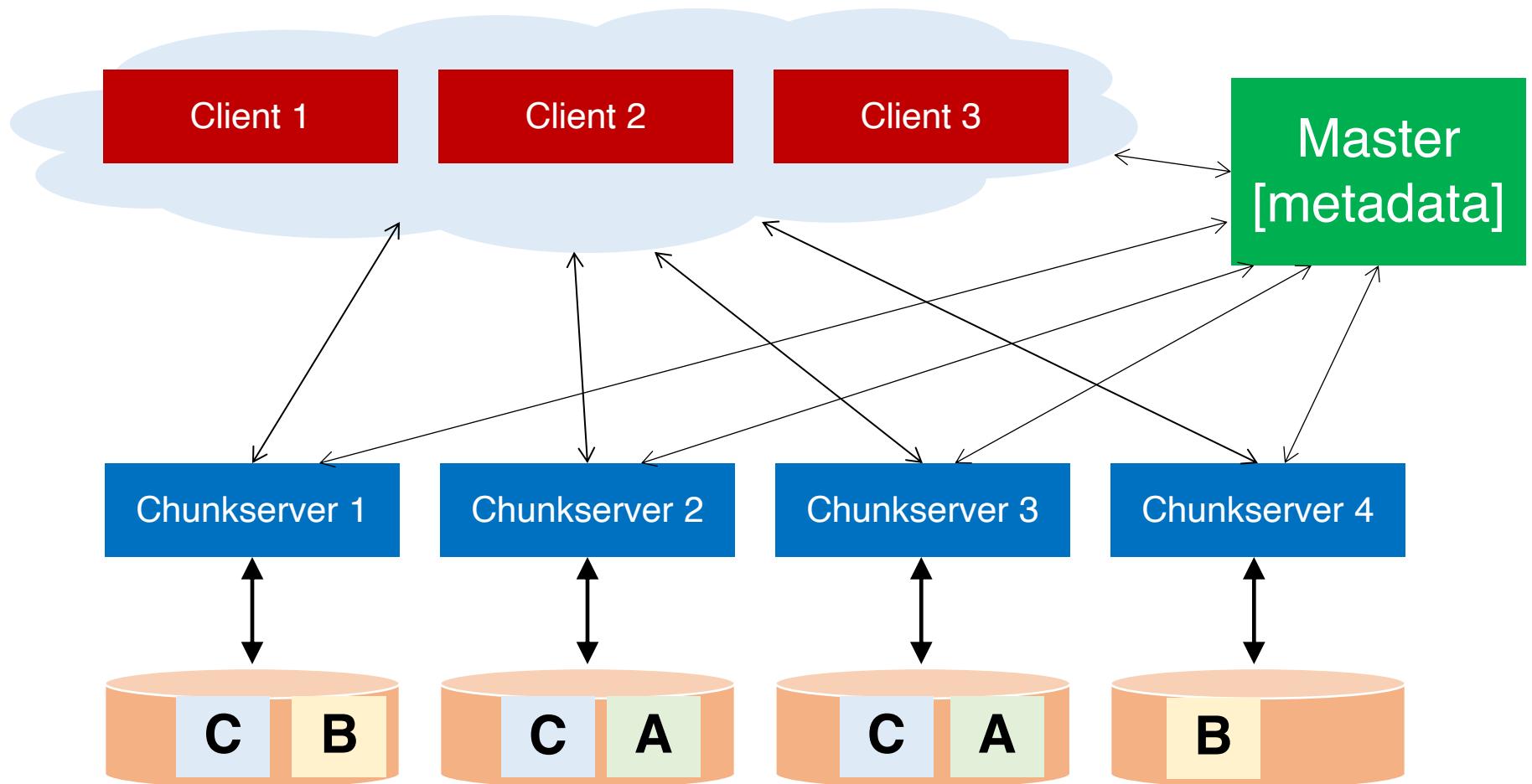
9. Client OS receives the reply and passes up to stub

10. Client stub unmarshals return value, returns to client



# Back to GFS

# GFS architecture: physical view



# Data chunks

- Break large GFS files into **coarse-grained** data chunks (e.g., 64-128MB)
- GFS chunkservers store physical data chunks in **local Linux file system**
- **Centralized** master keeps track of mapping between logical and physical chunks

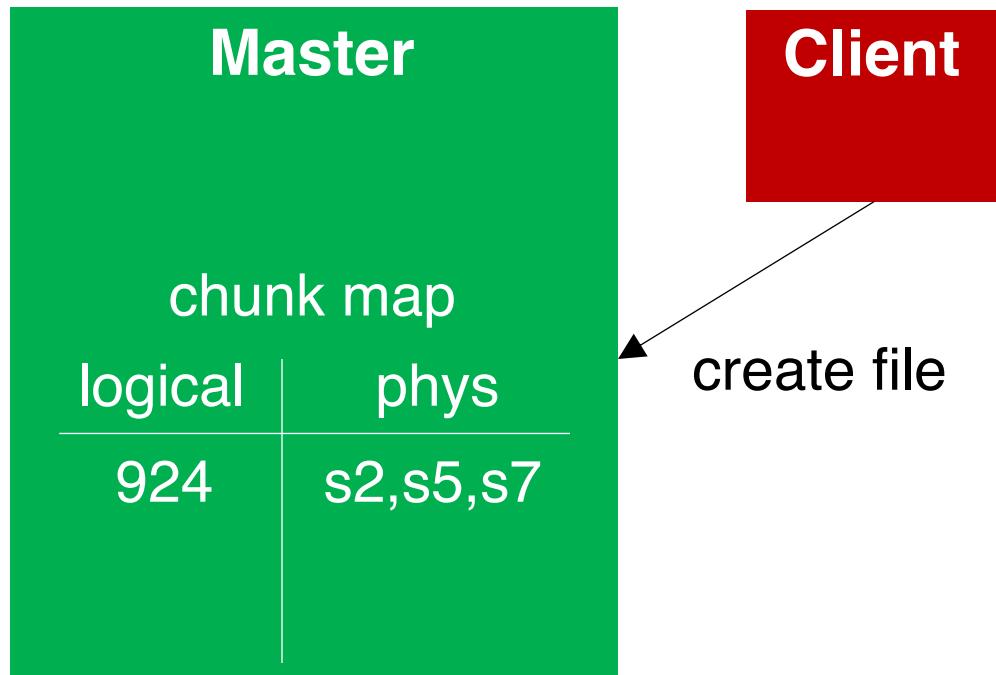
# HDFS demo

# Writing to a file

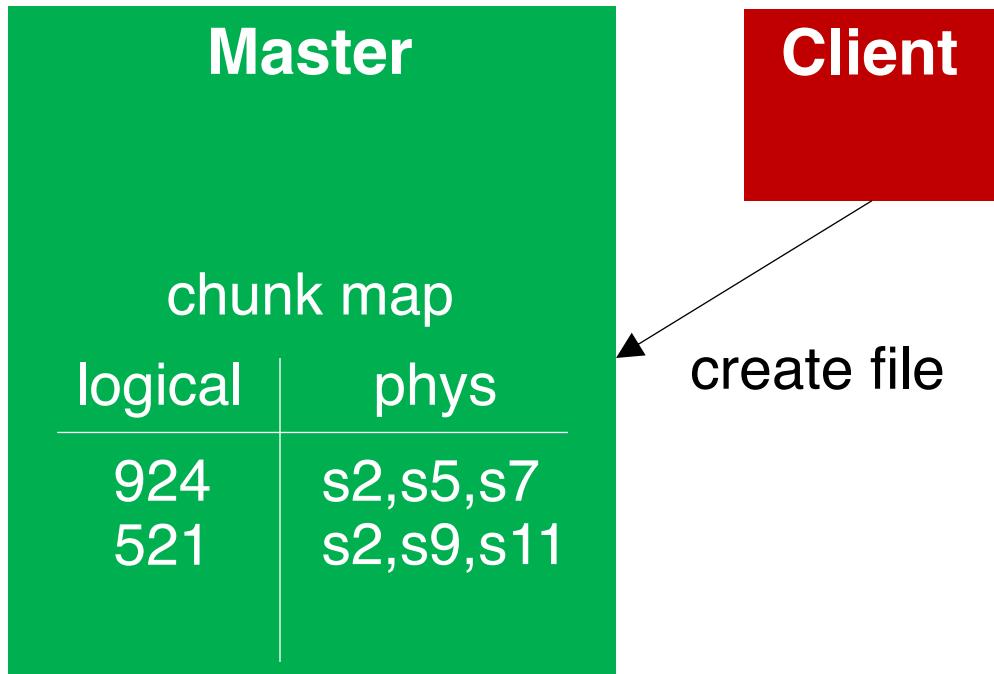
# Chunk map: the metadata

Master	
chunk map	
logical	phys
924	s2,s5,s7

# Client contacts the GFS master



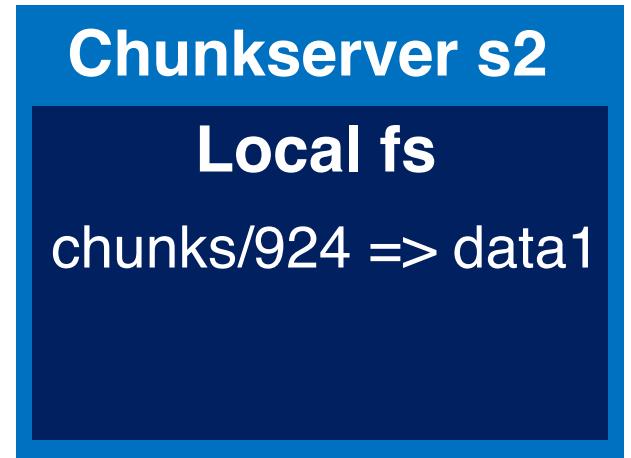
# GFS master creates file metadata



# Client writes replicas to chunkservers

Master	
chunk map	
logical	phys
924	s2,s5,s7
521	s2,s9,s11

Client



# Client writes replica to s2

Master	
chunk map	
logical	phys
924	s2,s5,s7
521	s2,s9,s11

write a chunk  
of 64MB

Client

Chunkserver s2

Local fs

chunks/924 => data1  
chunks/521 => data2

# S2 streams replica to s9

Master	
chunk map	
logical	phys
924	s2,s5,s7
521	s2,s9,s11

**Client**

replicate a  
chunk  
of 64MB

**Chunkserver s2**

**Local fs**

chunks/924 => data1  
chunks/521 => data2

**Chunkserver s9**

**Local fs**

chunks/521 => data1

# S9 streams replica to s11

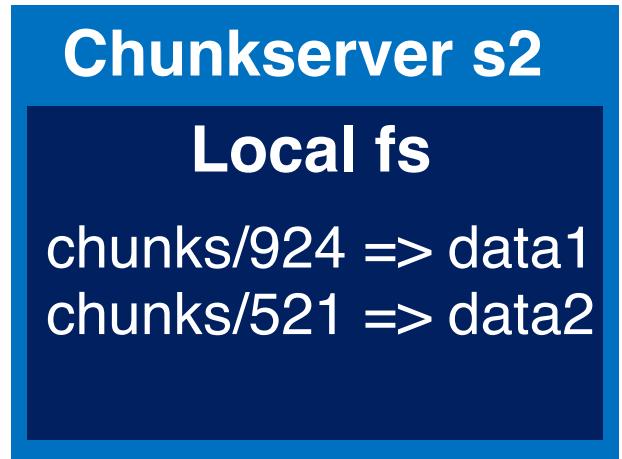
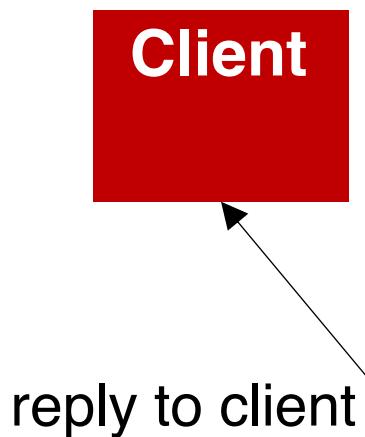
Master	
chunk map	
logical	phys
924	s2,s5,s7
521	s2,s9,s11

Client



# Primary replica s9 acks back

Master	
chunk map	
logical	phys
924	s2,s5,s7
521	s2,s9,s11



# Reading a file

# Chunk map: the metadata

Master	
chunk map	
logical	phys
924	s2,s5,s7
521	s2,s9,s11
...	...

# Chuckservers {s2,s5,s7} hold a data chunk

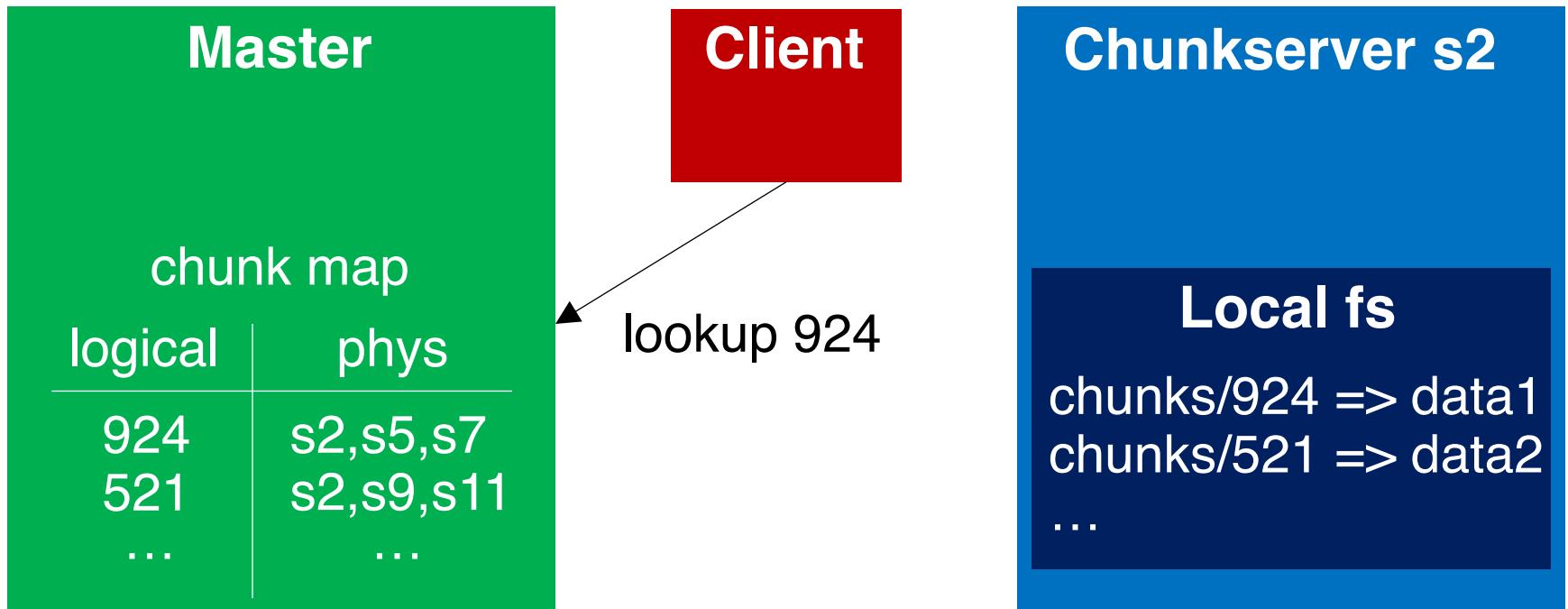
chunk map	
logical	phys
924	s2,s5,s7
521	s2,s9,s11
...	...

Chunkserver s2

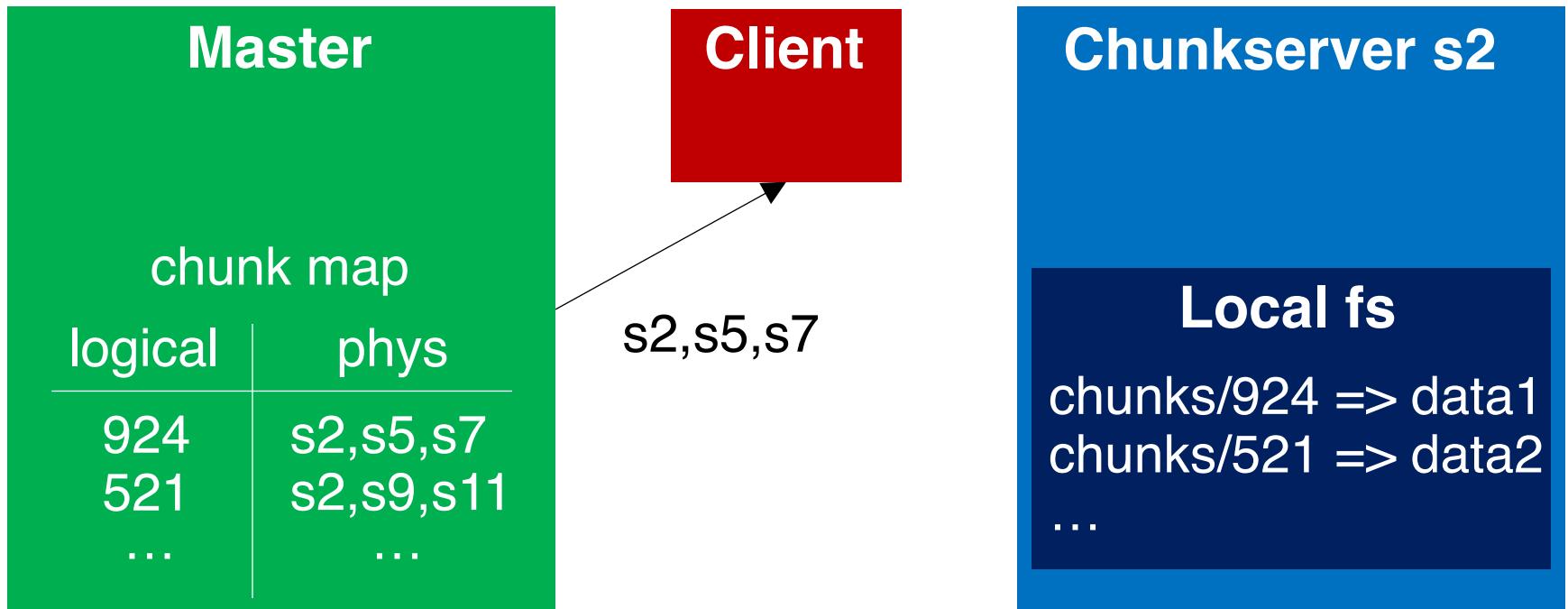
Local fs

chunks/924 => data1  
chunks/521 => data2  
...

# Client asks for the location



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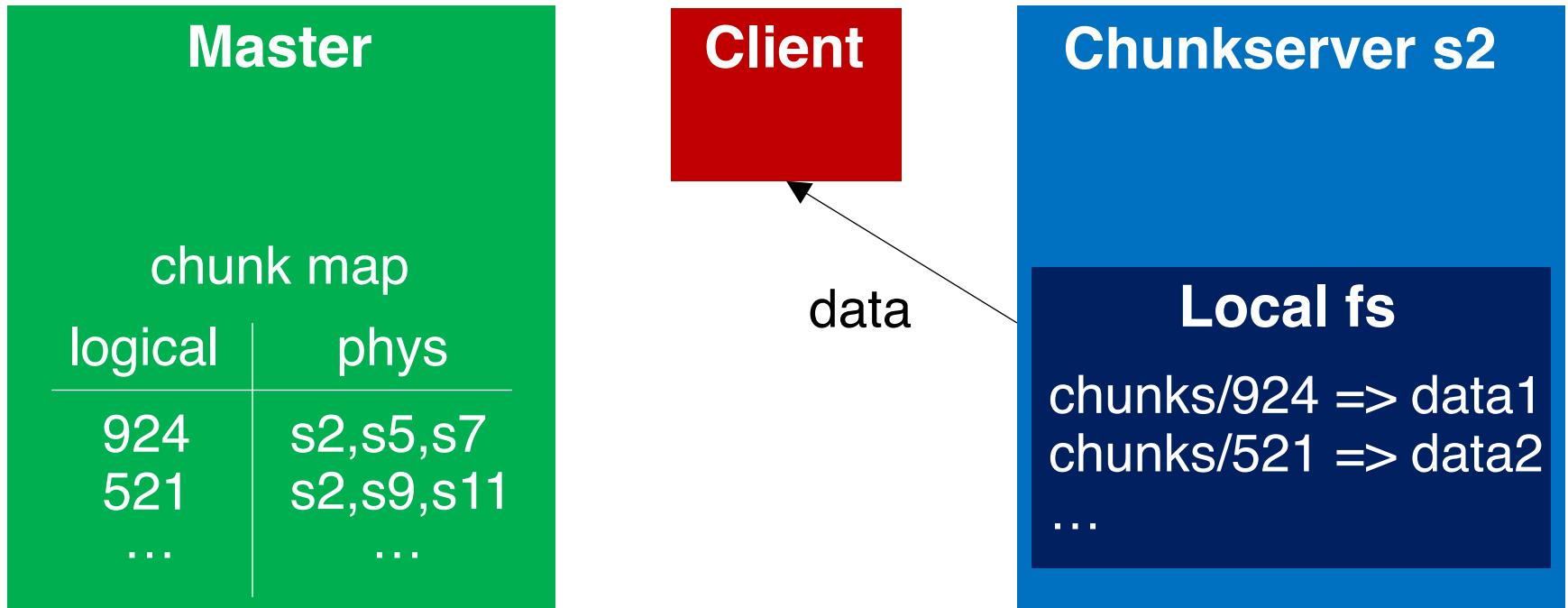
# Client reads a chunk



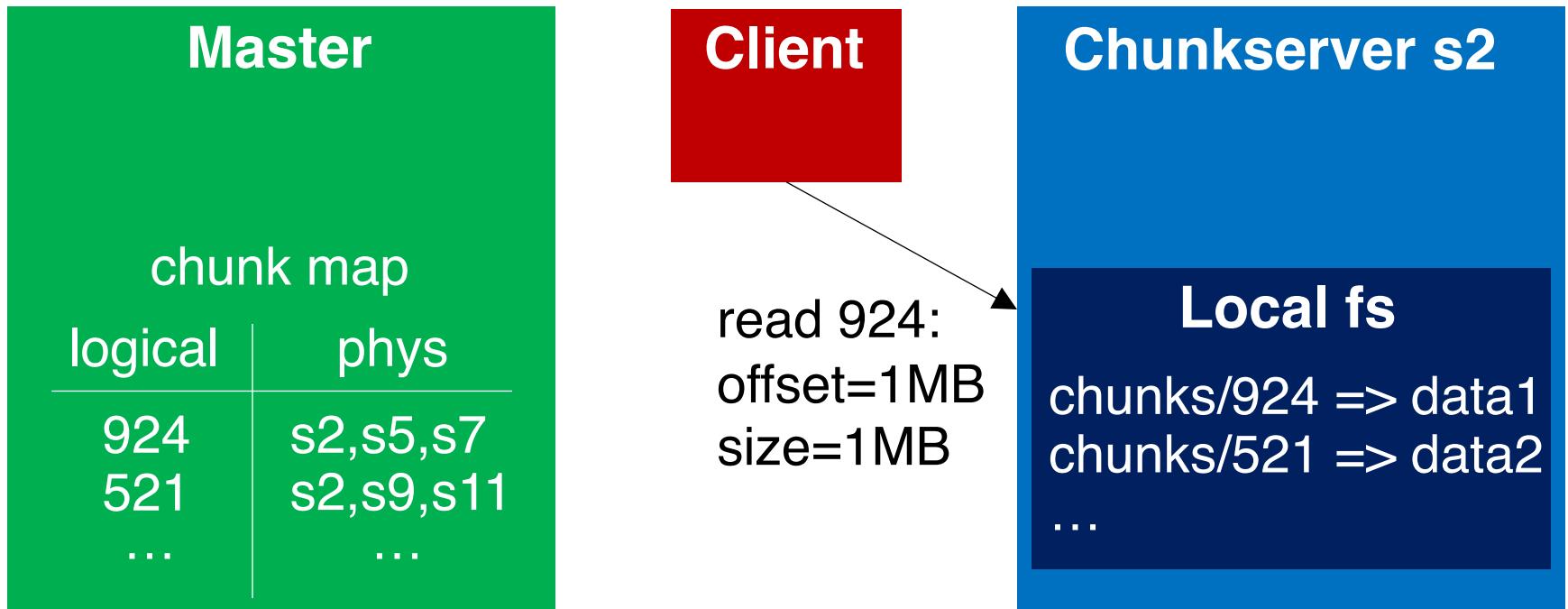
# Client reads a chunk



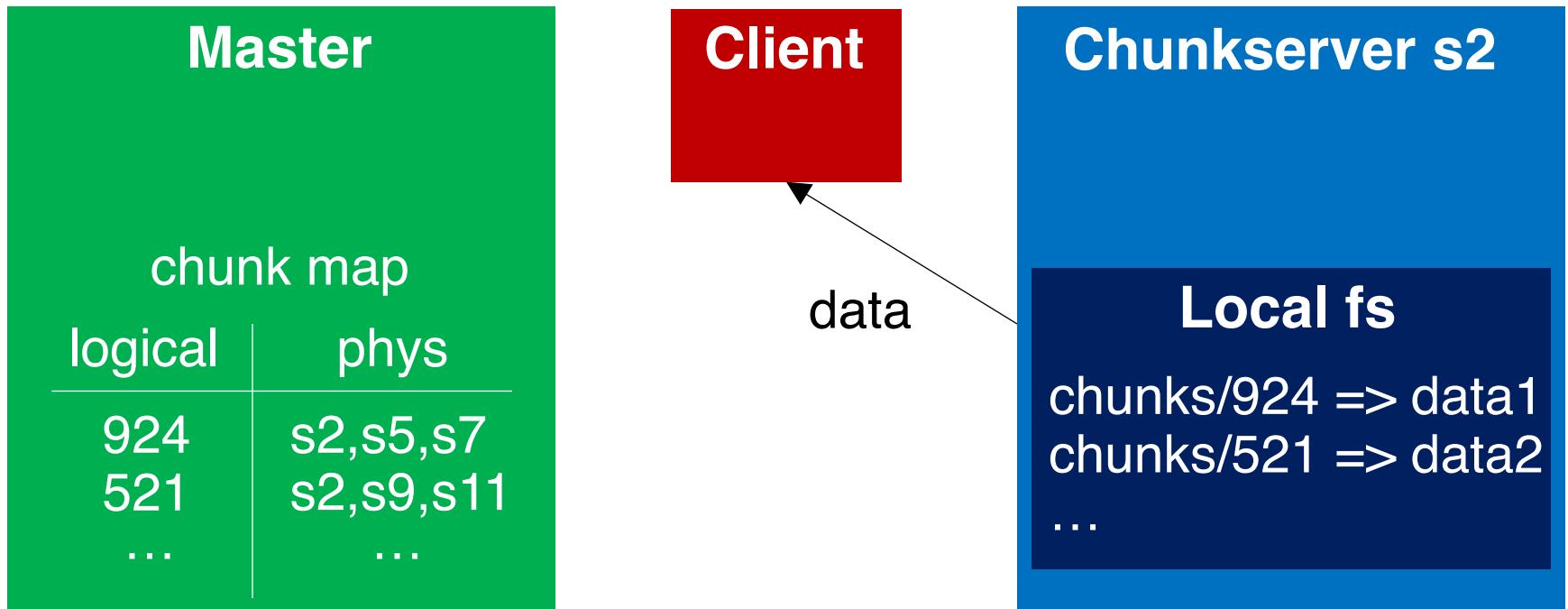
# Client reads a chunk



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# Client reads a chunk



# File namespace

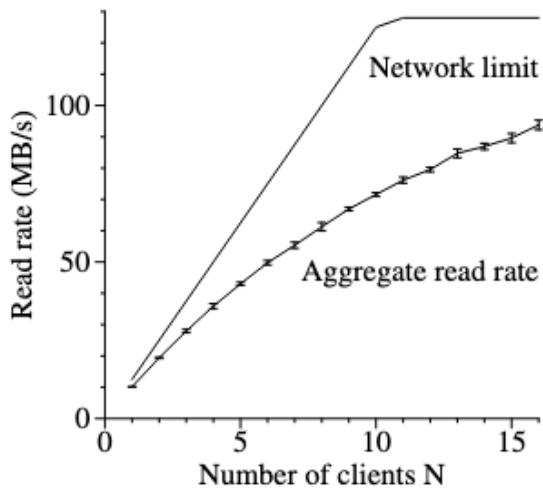


path names mapped to logical names

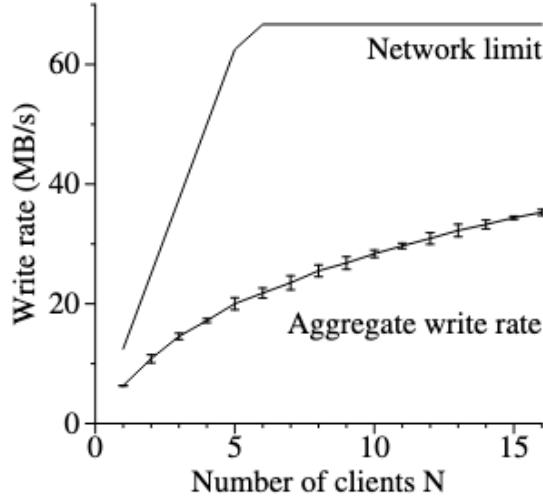
# Discussion

# GFS evaluation

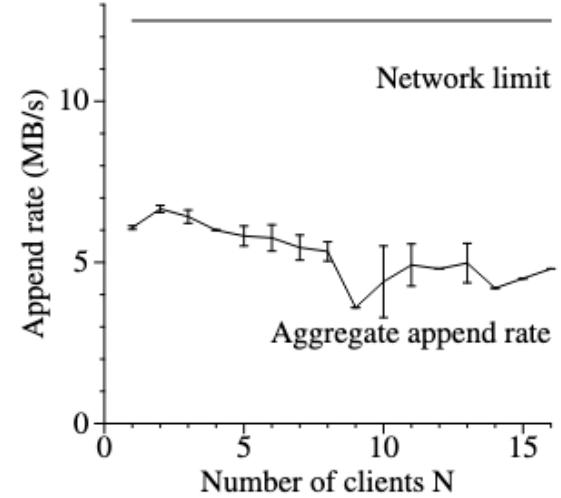
List your takeaways from “Figure 3: Aggregate Throughputs”



(a) Reads



(b) Writes



(c) Record appends

# GFS scale

The evaluation in Table 2 shows clusters with up to 180 TB of data. What part of the design/configuration would need to change if we instead had **180 PB of data**?

Cluster	A	B
Chunkservers	342	227
Available disk space	72 TB	180 TB
Used disk space	55 TB	155 TB
Number of Files	735 k	737 k
Number of Dead files	22 k	232 k
Number of Chunks	992 k	1550 k
Metadata at chunkservers	13 GB	21 GB
Metadata at master	48 MB	60 MB

**Table 2: Characteristics of two GFS clusters**