

Concurrency Overview

CS 475: Concurrent & Distributed Systems (Fall 2021)
Lecture 2

Yue Cheng

Some material taken/derived from:

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Concurrency

Process vs. thread

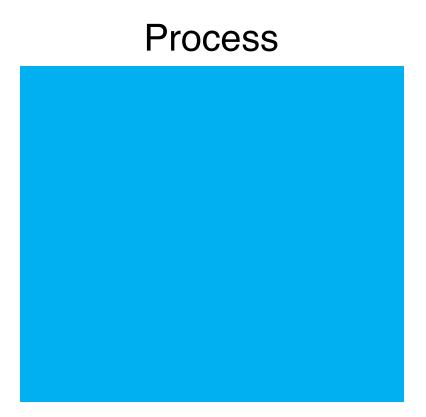
Race conditions

Locks

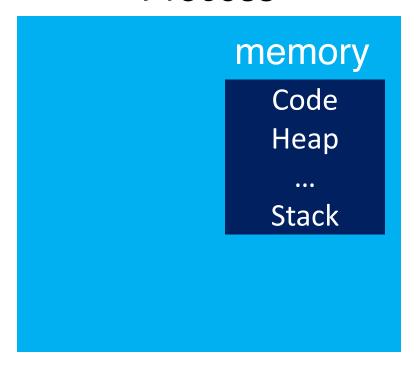
• Concurrency in Go

- Programs are code (static entity)
- Processes are running programs

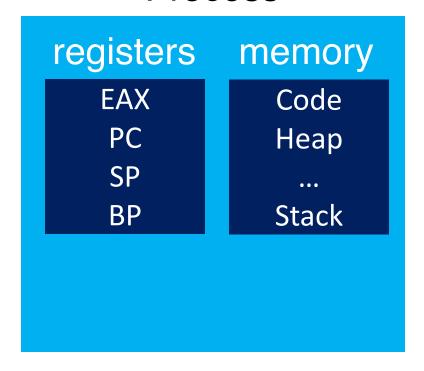
- Java analogy
 - class -> "program"
 - object -> "process"

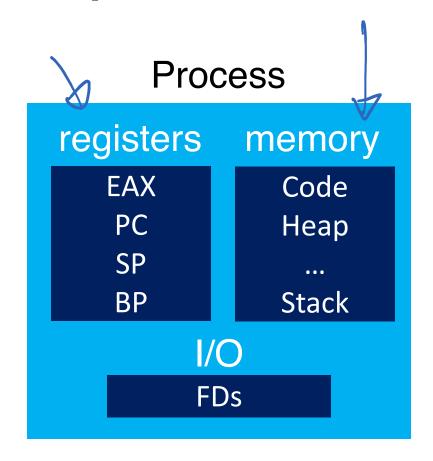


Process



Process





Peeking inside

- Processes share code, but each has its own "context"
- CPU
 - Instruction pointer (Program Counter)
 - Stack pointer
- Memory
 - Set of memory addresses ("address space")
 - cat /proc/<PID>/maps
- Disk
 - Set of file descriptors
 - cat /proc/<PID>/fdinfo/*

Threads

Why thread abstraction?

Process abstraction: Challenge 1

• Inter-process communication (IPC)

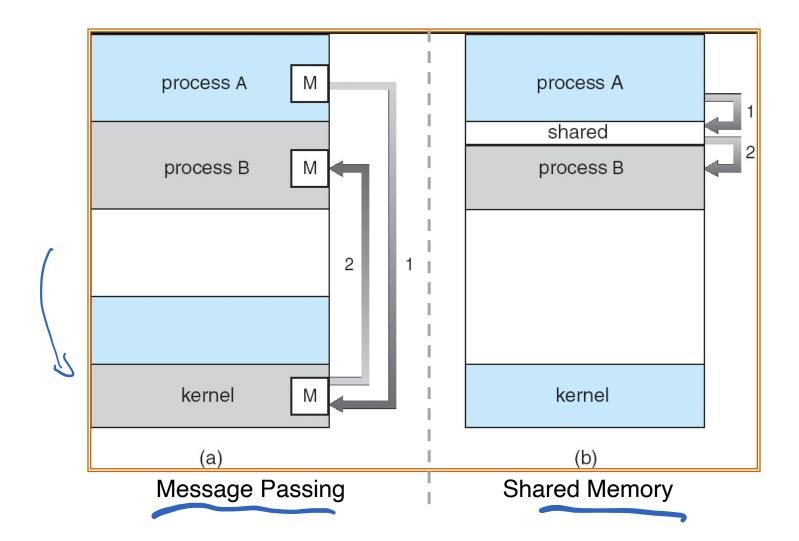
Inter-process communication

 Mechanism for processes to communicate and to synchronize their actions

- Two models
 - Communication through a shared memory region
 - Communication through message passing



Communication models



Communication through message passing

- Message system processes communicate with each other without resorting to shared variables
- A message-passing facility must provide at least two operations:
 - send(message, recipient)
 - receive(message, sender)
- With indirect communication, the messages are sent to and received from mailboxes (or, ports)
 - send(A, message) /* A is a mailbox */
 - receive(A, message)

Communication through message passing

- Message passing can be either blocking (synchronous) or non-blocking (asynchronous)
 - Blocking Send: The sending process is blocked until the message is received by the receiving process or by the mailbox
 - Non-blocking Send: The sending process resumes the operation as soon as the message is received by the kernel
 - Blocking Receive: The receiver blocks until the message is available
 - Non-blocking Receive: "Receive" operation does not block; it either returns a valid message or a default value (null) to indicate a non-existing message

Communication through shared memory

- The memory region to be shared must be explicitly defined
- System calls (Linux):
 - shmget creates a shared memory block
 - shmat maps/attaches an existing shared memory block into a process's address space
 - shmdt removes ("unmaps") a shared memory block from the process's address space
 - shmctl is a general-purpose function allowing various operations on the shared block (receive information about the block, set the permissions, lock in memory, ...)
- Problems with simultaneous access to the shared variables

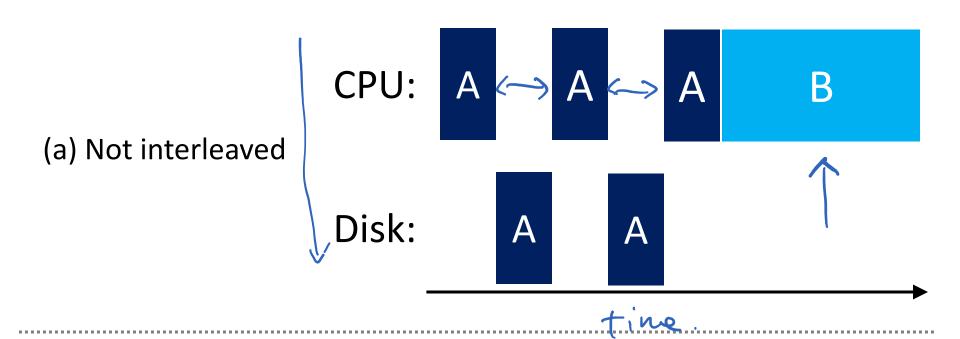
Process abstraction: Challenge 1

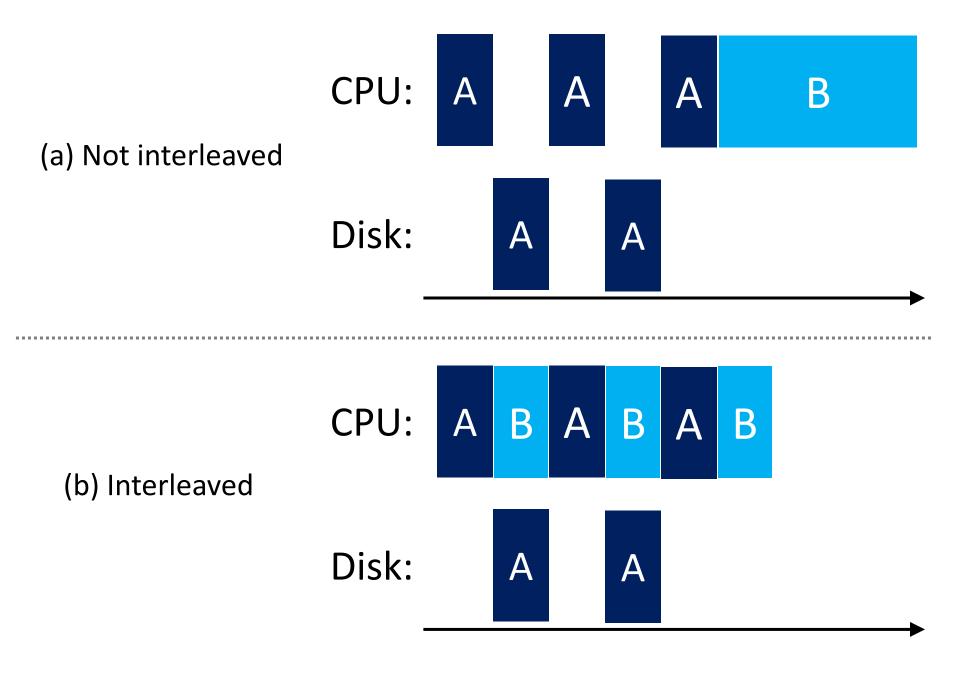
- Inter-process communication (IPC)
 - Cumbersome programming!
- ~
- Copying overheads (inefficient communication)
- Expensive context switching (why expensive?)

Process Abstraction: Challenge 2

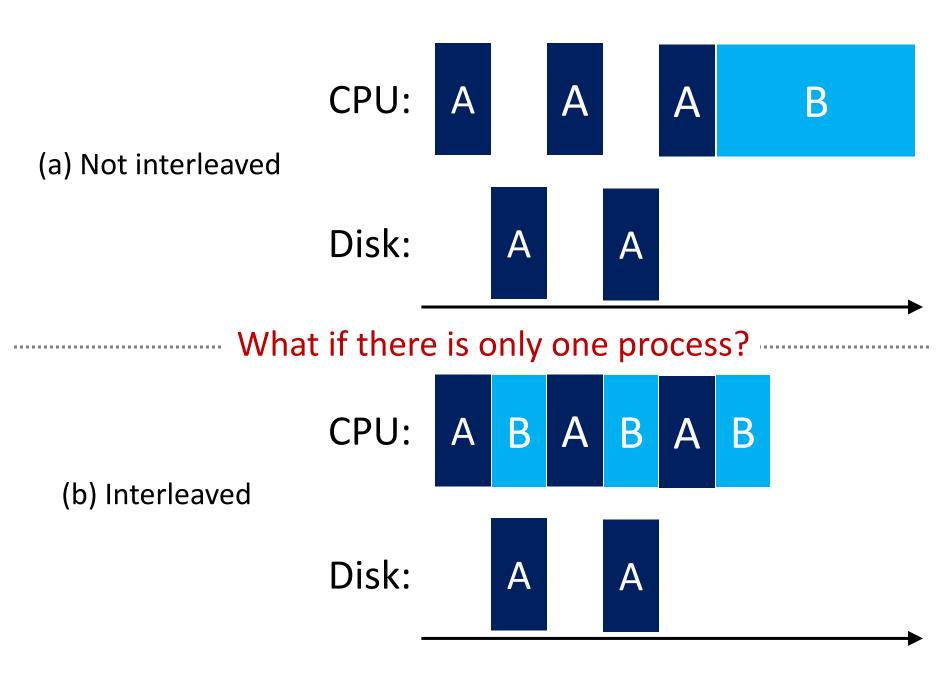
- Inter-process communication (IPC)
 - Cumbersome programming!
 - Copying overheads (inefficient communication)
 - Expensive context switching (why expensive?)

CPU utilization





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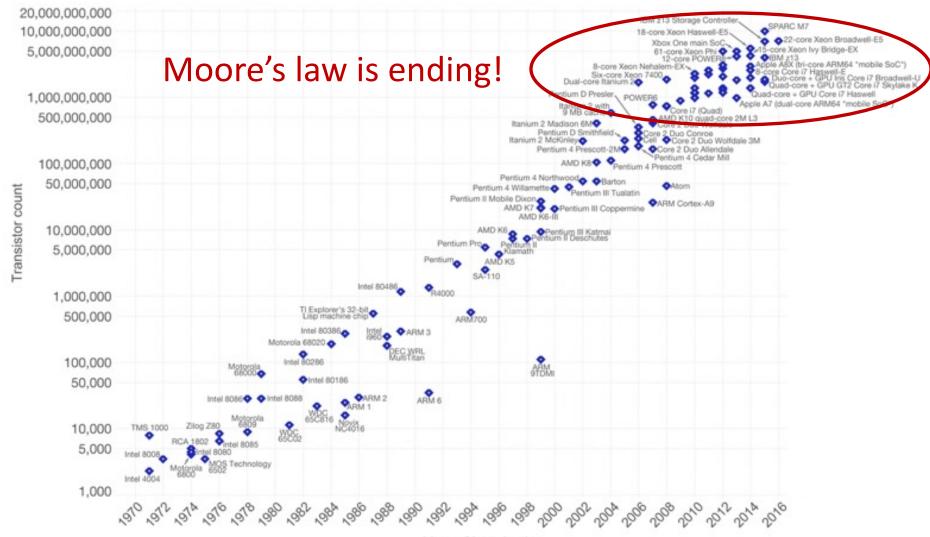
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Moore's law: # transistors doubles every ~2 years

Moore's Law – The number of transistors on integrated circuit chips (1971-2016) Our World



Moore's law describes the empirical regularity that the number of transistors on integrated circuits doubles approximately every two years. This advancement is important as other aspects of technological progress - such as processing speed or the price of electronic products - are strongly linked to Moore's law.



CPU trends – What Moore's Law implies...

- The future
 - Same CPU speed
 - More cores (to scale-up or scale-out)

Faster programs => concurrent execution

 Goal: Write applications that fully utilize many CPU cores...

Goal

• Write applications that fully utilize many CPUs...

Strategy 1

- Build applications from many communication processes
 - Like Chrome (process per tab)
 - Communicate via pipe() or similar

• Pros/cons?

Strategy 1

- Build applications from many communication processes
 - Like Chrome (process per tab)
 - Communicate via pipe() or similar
- Pros/cons? That we've talked about in previous slides
 - Pros:
 - Don't need new abstractions!
 - Better (fault) isolation?
 - Cons:
 - Cumbersome programming using IPC
 - Copying overheads
 - Expensive context switching

Strategy 2

New abstraction: the thread

Introducing thread abstraction

New abstraction: the thread

 Threads are just like processes, but threads share the address space

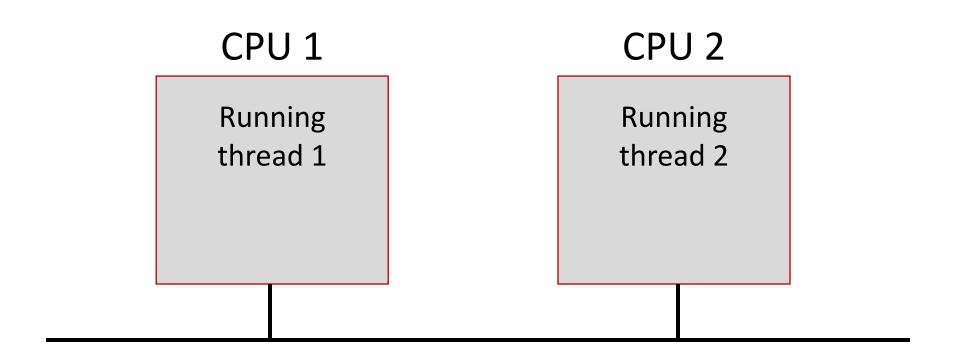
Thread

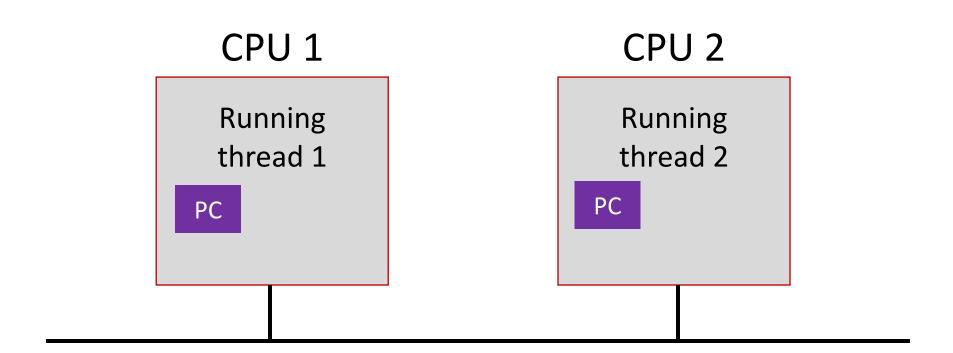
 A process, as defined so far, has only one thread of execution

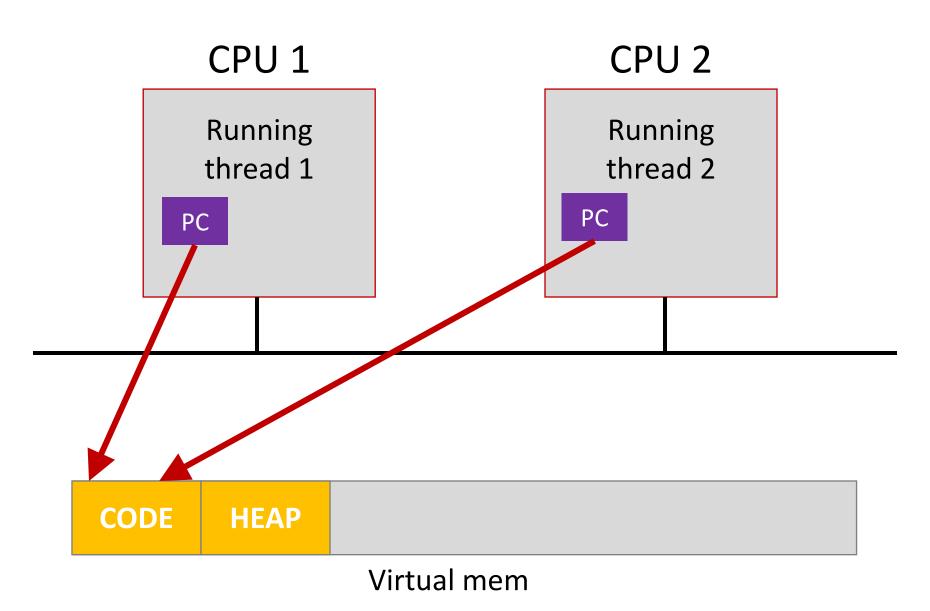
- Idea: Allow multiple threads of concurrently running execution within the same process environment, to a large degree independent of each other
 - Each thread may be executing different code at the same time

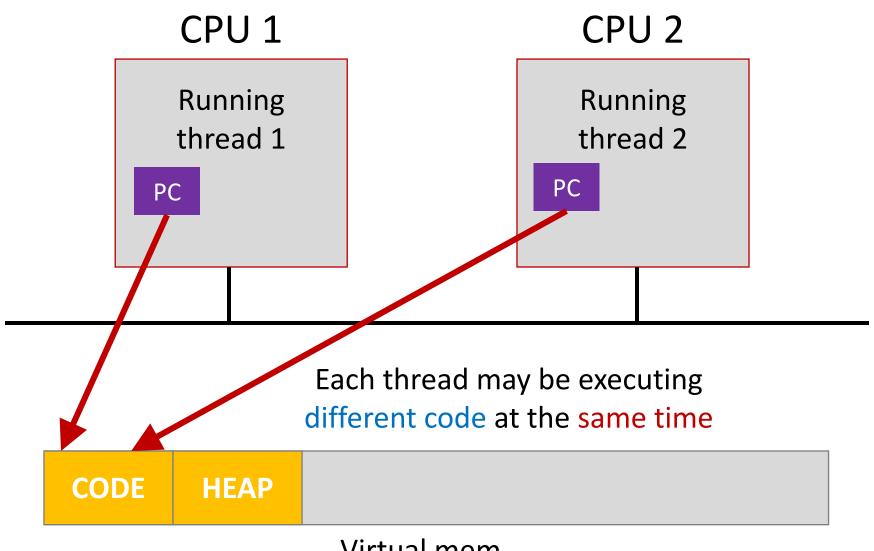
Process vs. Thread

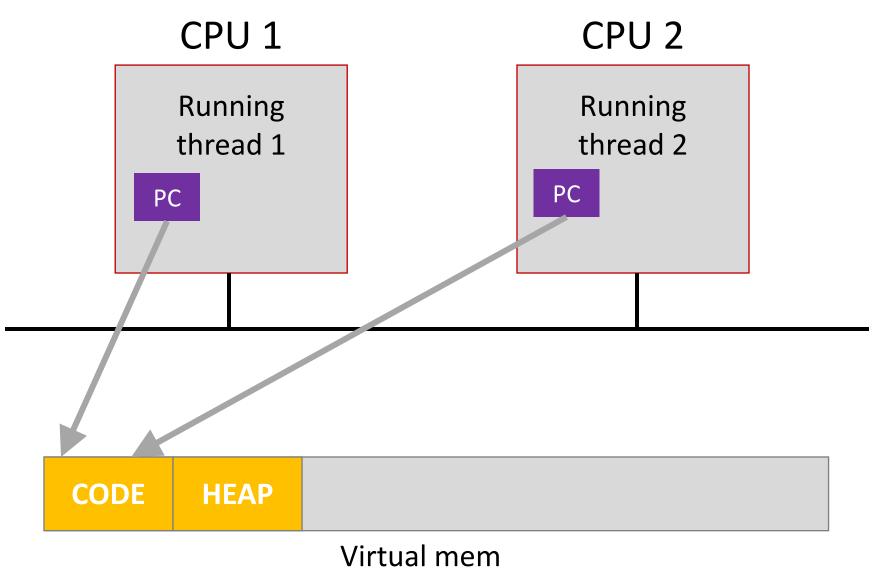
- Multiple threads within a process will share
 - The address space
 - Open files (file descriptors)
 - Other resources
- Thread
 - Efficient and fast resource sharing
 - Efficient utilization of many CPU cores with only one process
 - Less context switching overheads

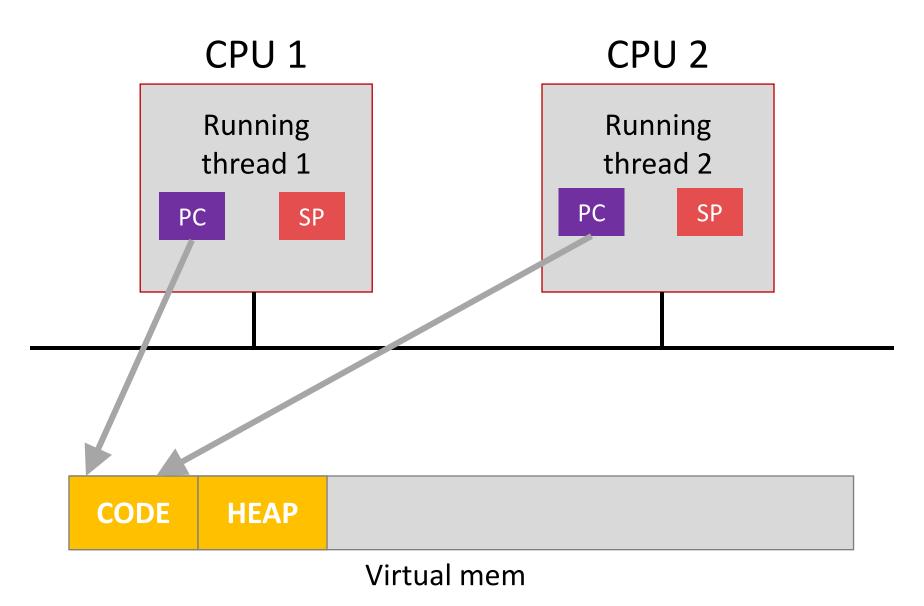


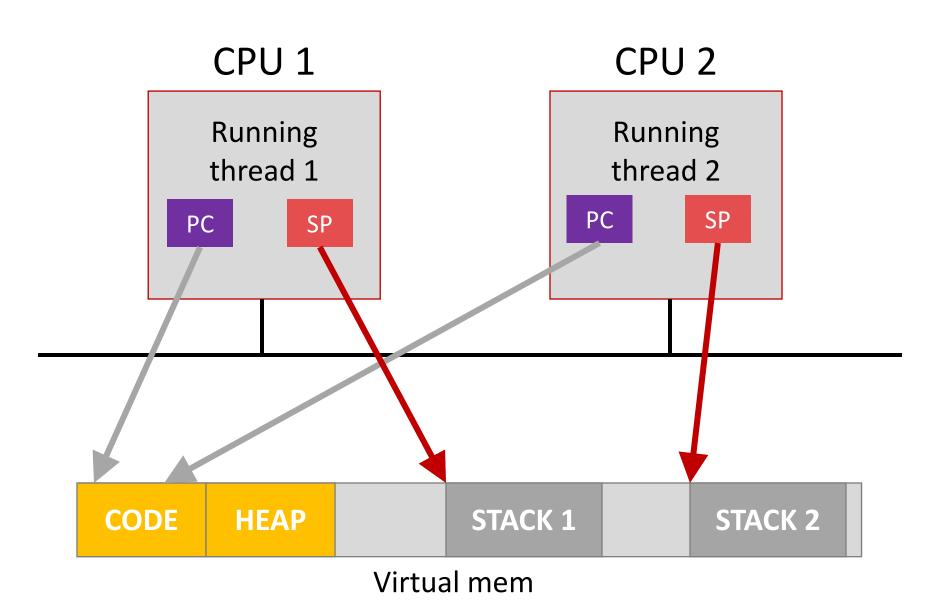




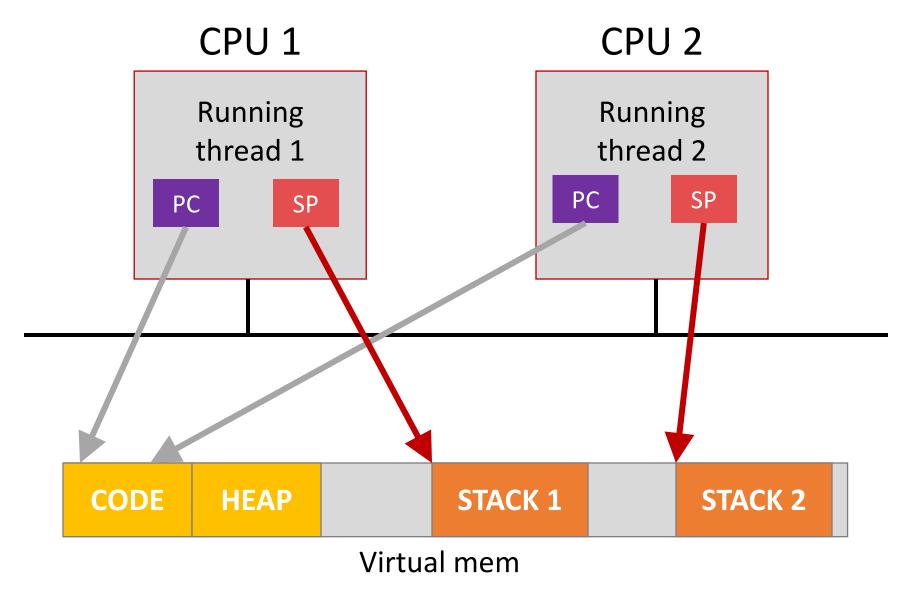


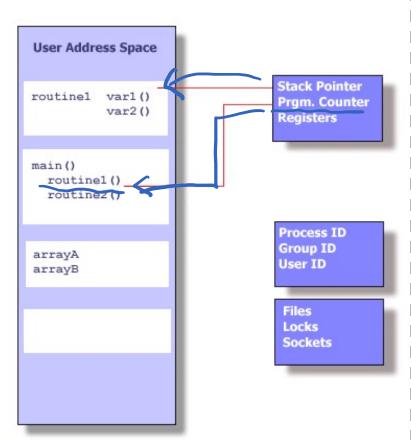


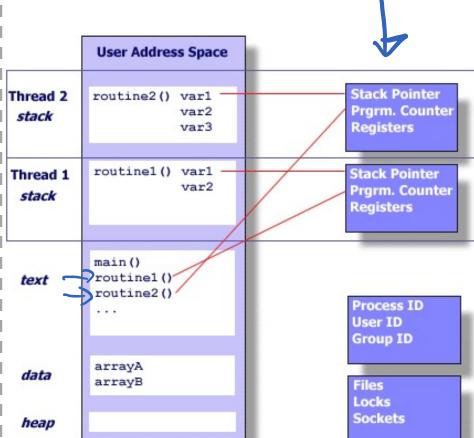




Thread executing different functions need different stacks







Threads within a Linux process

pthread.

Linux process

stack

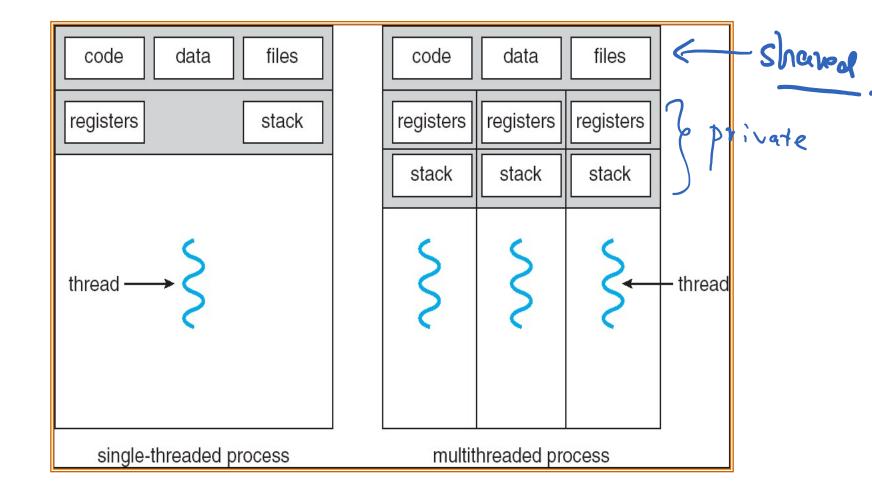
text

data

heap

^{*:} https://computing.llnl.gov/tutorials/pthreads/

Single- vs. Multi-threaded Process



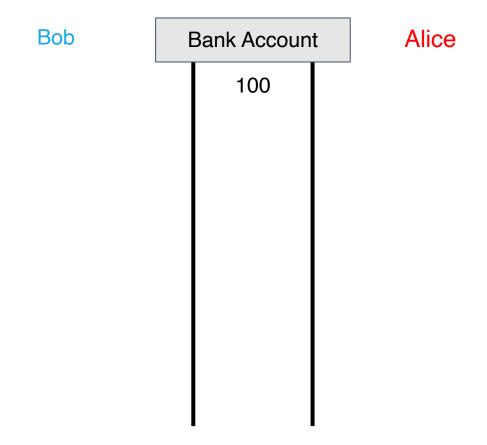
Concurrency

Process vs. thread

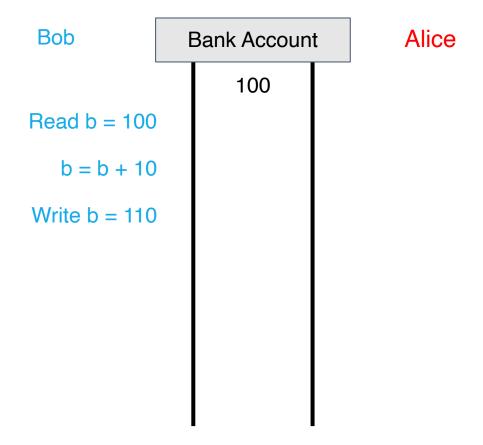
Race conditions

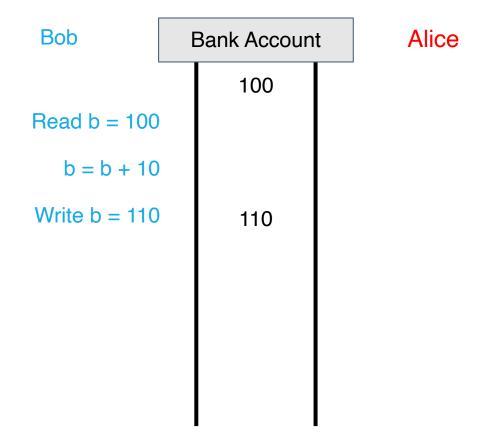
• Locks

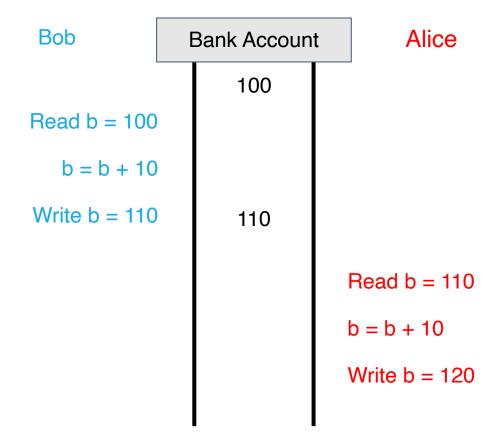
• Concurrency in Go

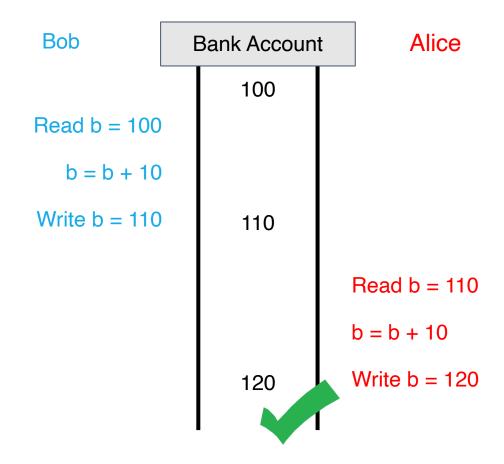


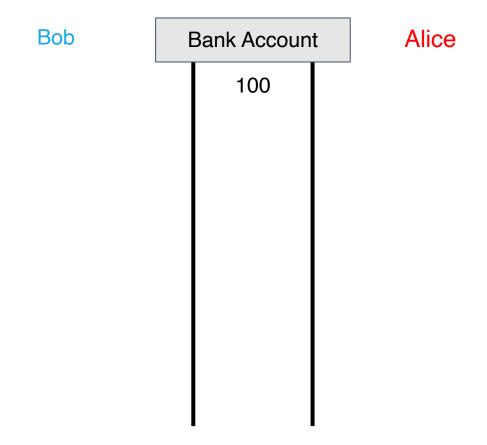
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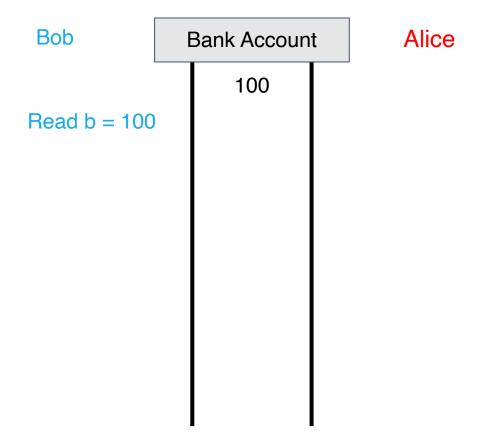


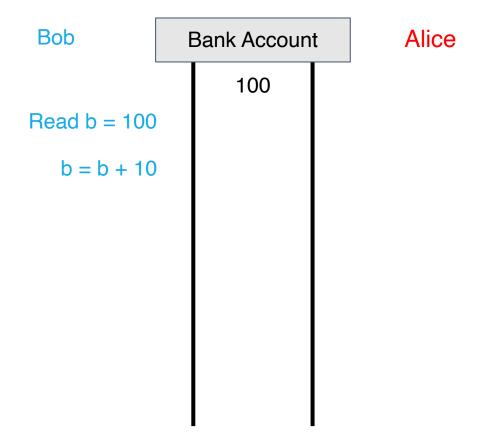


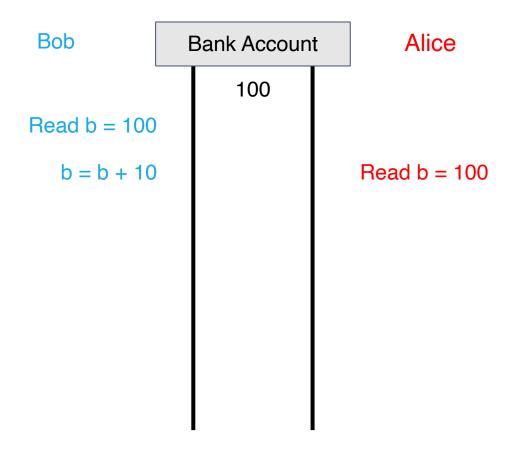


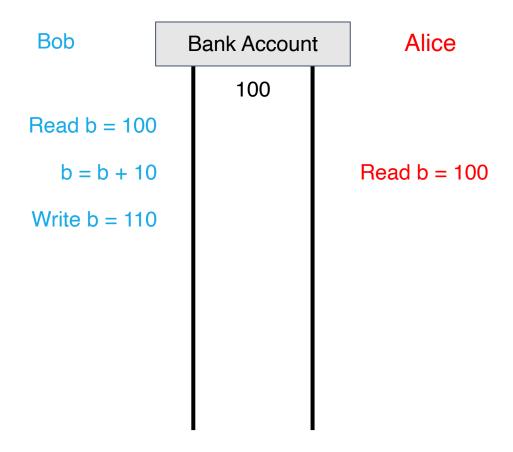


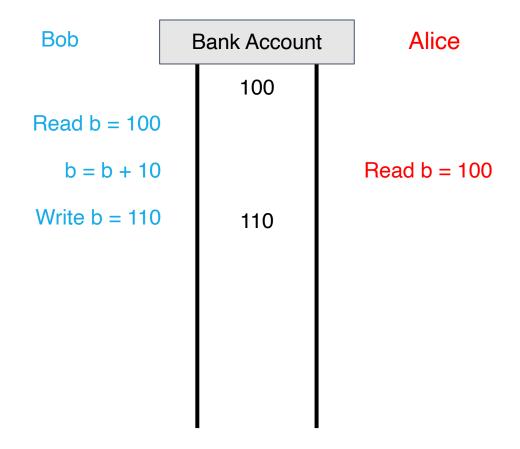


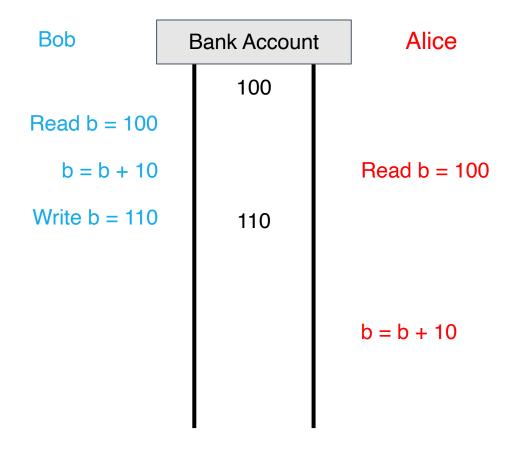


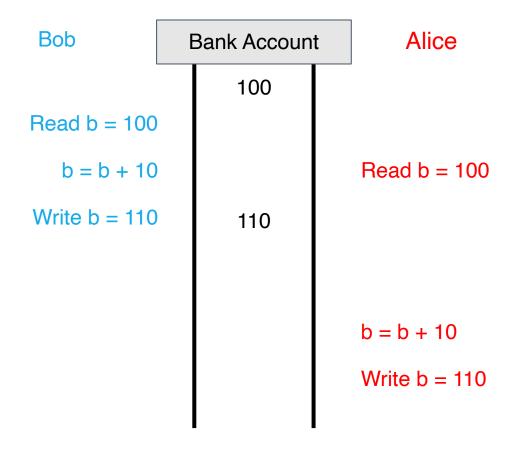


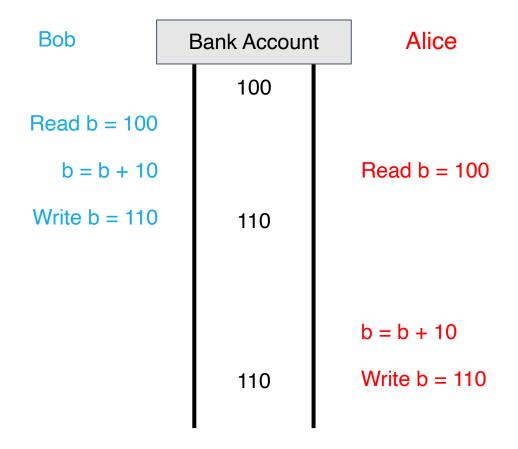


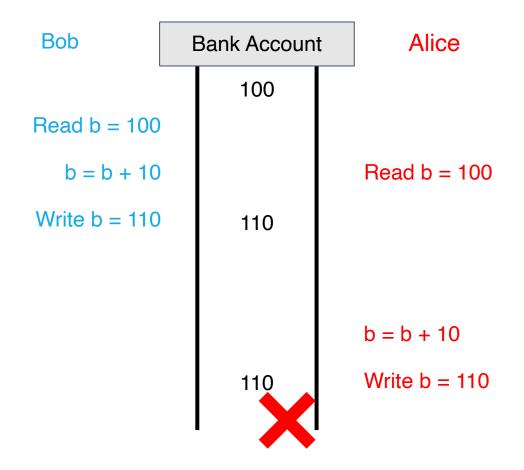












What went wrong?

• Changes to balance are not atomic

Root cause: Let's look at a C example...

```
#include <stdio.h>
    #include "common.h"
    static volatile int counter = 0; Threaded counting example
    11
    // mythread()
    // Simply adds 1 to counter repeatedly, in a loop
    // No, this is not how you would add 10,000,000 to
10
    // a counter, but it shows the problem nicely.
11
    11
12
    void *mythread(void *arg)
13
14
        printf("%s: begin\n", (char *) arg);
15
16
        int i;
        for (i = 0; i < 1e7;)i++) {
            counter = counter + 1;
18
19
20
        printf("%s: done\n", (char*) arg);
        return NULL;
                                              git clone https://github.com/tddg/demo-ostep-code
22
                                              cd demo-ostep-code/threads-intro
                                            $ make
24
    11
25
    // main()
                                              ./t1 <loop count>
26
    11
27
    // Just launches two threads (pthread_create)
                                                                          Try it yourself
    // and then waits for them (pthread_join)
    //
30
    int main(int argc, char *argv[])
32
        pthread_t p1, p2;
        printf("main: begin (counter = %d)\n", counter);
33
34
     Pthread_create(&p1, NULL, mythread, "A");
        Pthread_create(&p2, NULL, mythread, "B");
36
        // join waits for the threads to finish
38
        Pthread_join(p1, NULL);
```

17

31

35

39

40

41

42

Pthread_join(p2, NULL);

return 0;

printf("main: done with both (counter = %d)\n", counter);

Back-to-back runs

```
Run 1...
main: begin (counter = 0)
A: begin
B: begin
A: done
B: done
main: done with both (counter = 10706438)
Run 2...
main: begin (counter = 0)
A: begin
B: begin
A: done
B: done
main: done with both (counter = 11852529)
```

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What exactly happened??

What exactly happened??

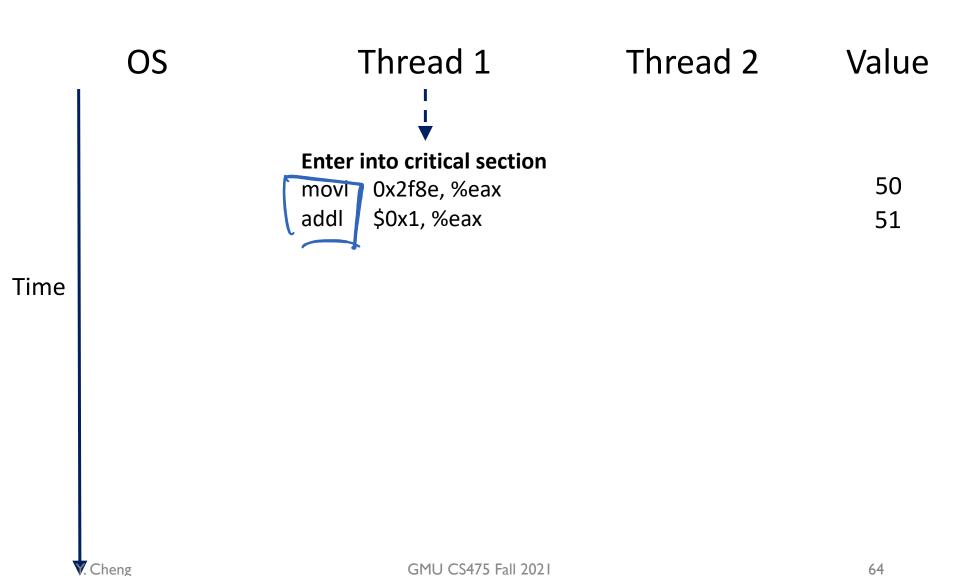
```
% otool -t -v thread_rc
% objdump -d thread_rc
```

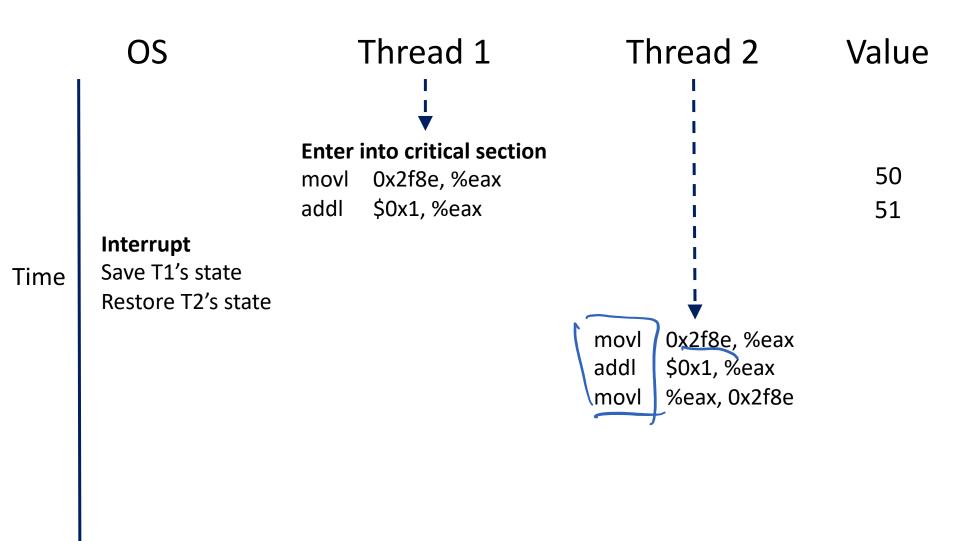
```
[Mac OS X]
[Linux]
```

```
000000100000d52 movl 0x2f8e %eax
000000100000d58 addl $0x1, %eax
000000100000d5b movl %eax, 0x2f8e
```

• •

counter = counter + 1;

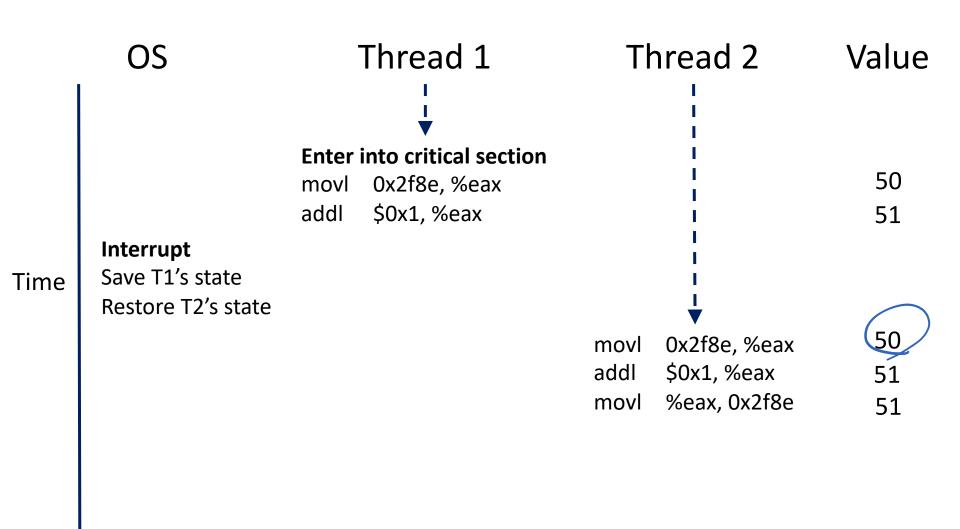




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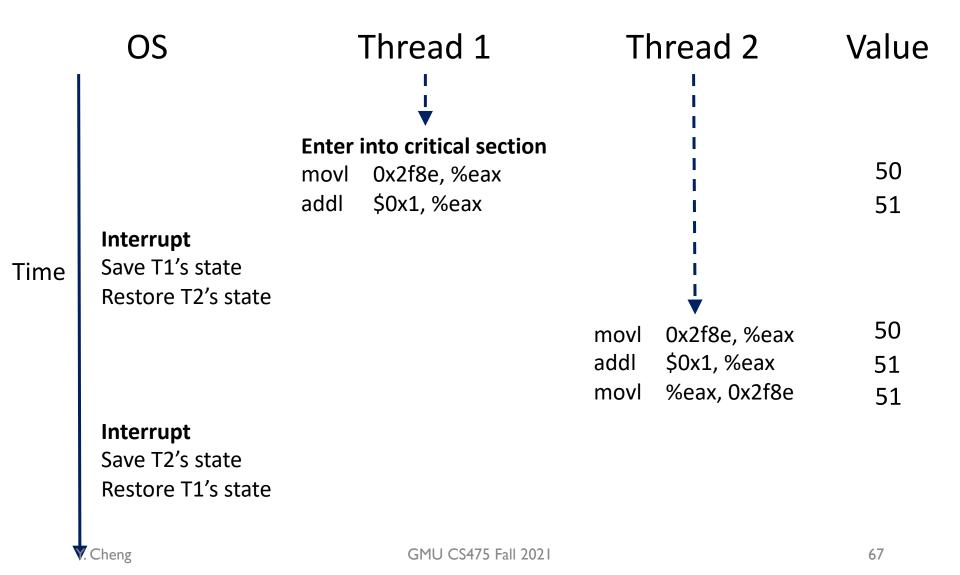
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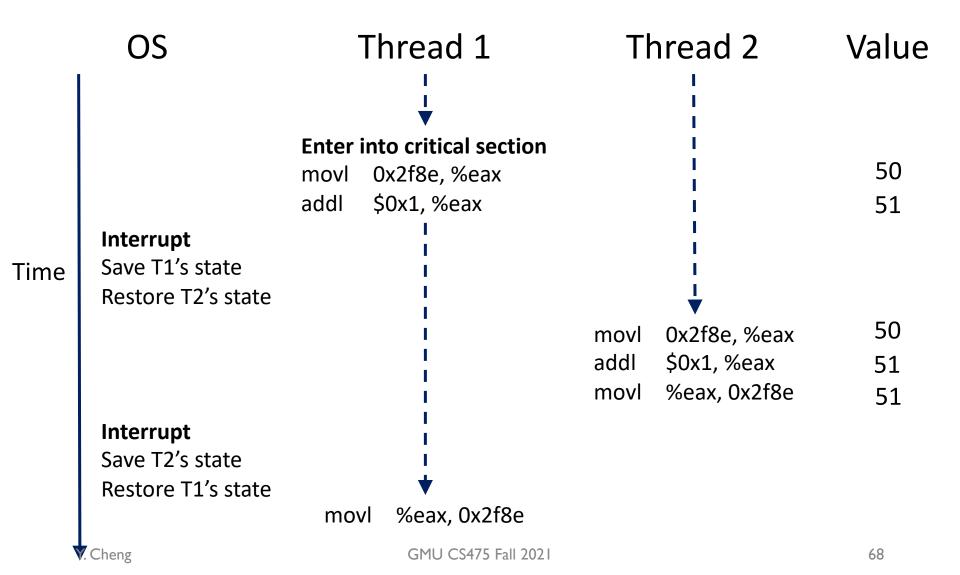


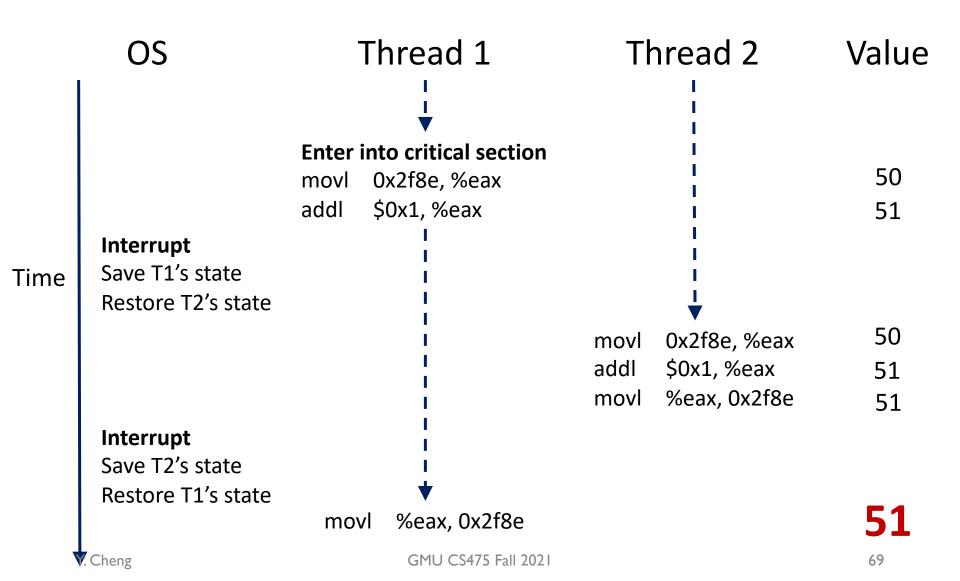
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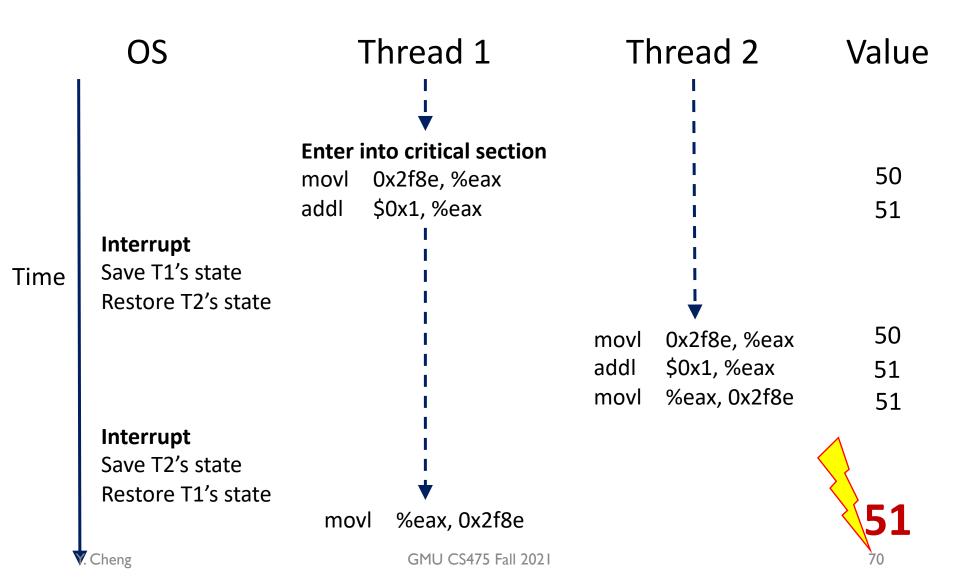
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Race conditions

- Observe: In a time-shared system, the exact instruction execution order cannot be predicted
 - Deterministic vs. Non-deterministic

 Any possible orders can happen, which result in different output across runs

Race conditions

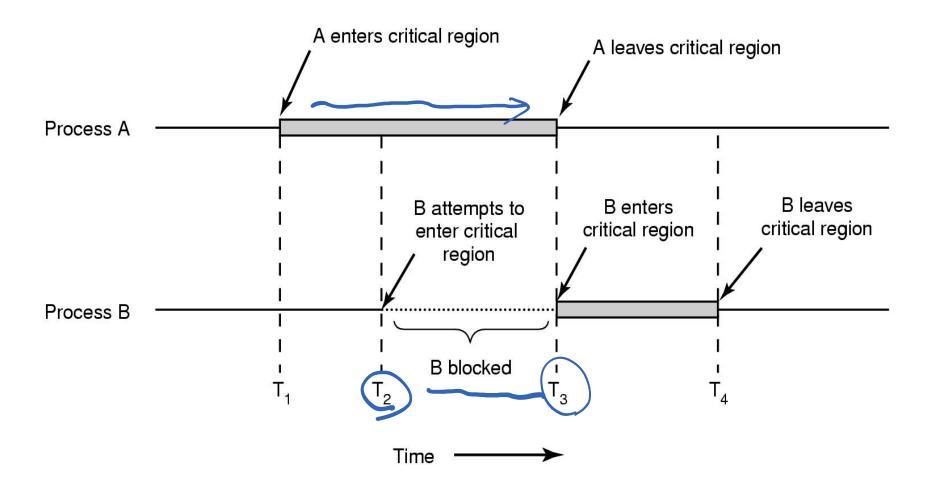
- Situations like this, where multiple threads are writing or reading some shared data and the final result depends on who runs precisely when, are called race conditions
 - A serious problem for any concurrent system using shared variables

- Programmers must make sure that some highlevel code sections are executed atomically
 - Atomic operation: It completes in its entirety without worrying about interruption by any other potentially conflict-causing thread

The critical-section problem

- N threads all competing to access the shared data
- Each process/thread has a code segment, called critical section (critical region), in which the shared data is accessed
- Problem ensure that when one thread is executing in its critical section, no other thread is allowed to execute in that critical section
- The execution of the critical sections by the threads must be mutually exclusive in time

Mutual exclusion



Solving critical-section problem

Any solution to the problem must satisfy four conditions!

Mutual Exclusion:

No two threads may be simultaneously inside the same critical section

Bounded Waiting:

No thread should have to wait forever to enter a critical section

Progress:

No thread executing a code segment unrelated to a given critical section can block another thread trying to enter the same critical section

Arbitrary Speed:

No assumption can be made about the relative speed of different threads (though all threads have a non-zero speed)

Locks

A lock is a variable

- Two states
 - Available or free
 - Locked or held
- 1 lock(): tries to acquire the lock
 - unlock(): releases the lock that has been acquired by caller

Using Lock to protect shared data

Changes to balance are not atomic

Thread A:

Thread B:

77

```
func Deposit(amount) {
    balanceLock.lock()
    read balance
    balance = balance + amount
    write balance
    balanceLock.unlock()
}
```

Using Lock to protect shared data

Changes to balance are not atomic

Thread A:

Thread B:

```
balance = balance + amount balance = balance + amount
```

```
func Deposit(amount) {
    balanceLock.lock()
    read balance
    balance = balance + amount
    write balance
    balanceLock.unlock()
}
```

Concurrency

- Process vs. thread
- Race conditions
- Locks
- Concurrency in Go
 - Two synchronization mechanisms
 - Locks
 - Channels

Two synchronization mechanisms in Go

- Locks: limit access to a critical section
 - Access to a critical section (e.g., shared variables) must be mutually exclusive

 Channels: pass information across threads using a queue

```
package account
import "sync"

type Account struct {
        balance int
        lock sync.Mutex
}
```

```
package account
import "sync"

type Account struct {
               balance int
                 lock sync.Mutex
}

func NewAccount(init int) Account
                return Account{balance: init}
}
```

```
func (a *Account) CheckBalance() int {
    a.lock.Lock()
    defer a.lock.Unlock()
    return a.balance
}
```

```
package account
import "sync"

type Account struct {
        balance int
        lock sync.Mutex
}

func NewAccount(init int) Account
        return Account{balance: init}
}
```

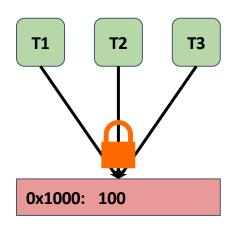
```
func (a *Account) CheckBalance() int {
     a.lock.Lock()
     defer a.lock.Unlock()
     return a.balance
func (a *Account) Withdraw(v int) {
     a.lock.Lock()
     defer a.lock.Unlock()
     a.balance -= v
func (a *Account) Deposit(v int) {
     a.lock.Lock()
     defer a.lock.Unlock()
     a.balance += v
```

Read write locks in Go

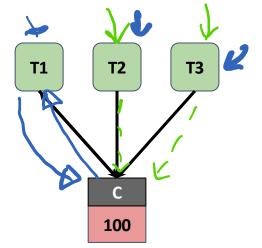
```
func (a *Account) CheckBalance() int {
    a.lock.RLock()
    defen a.lock.RUnlock()
      eturn a.balance
func (a *Account) Withdraw(v int)
     a.lock.Lock()
     defer a.lock.Unlock()
     a.balance -= v
func (a *Account) Deposit(v int)
     a.lock.Lock()
     defer a.lock.Unlock()
     a.balance += v
```

Two solutions to the same problem

- Locks:
 - Multiple threads can reference same memory location
 - Use lock to ensure only one thread is updating it at any time

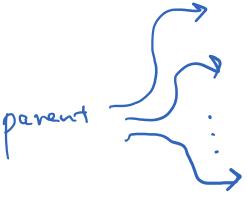


- Channels:
 - Data item initially stored in channel
 - Threads must request item from channel, make updates, and return item to channel



Go channels

 In Go, channels and goroutines are more idiomatic than locks



Go channels

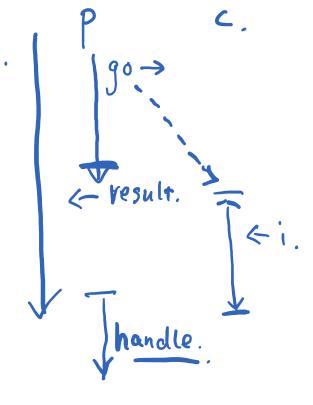
```
buffered channel.
```

 In Go, channels and goroutines are more idiomatic than locks

Go channels

```
result := make(chan int, numWorkers)
// Launch workers
for i := 0; i < numWorkers; i++ {</pre>
        go func() {
                 // ... do some work
                 result <- i
                                              time.
   Wait until all worker threads have finished
for i := 0; i < numWorkers; i++ {</pre>
        handleResult(<-result)
fmt.Println("Done!")
```

 In Go, channels and goroutines are more idiomatic than locks



Bank account code (using channels)

Bank account code (using channels)



```
func (a *Account) CheckBalance() int {
package account
                                         type Account struct {
                                         a.balance <- bal
      balance chan int
                                         return bal
                                     func (a *Account) Withdraw(v int) {
func NewAccount(init int) Account {
      a := Account make(chan int, 1)}
                                         bal := <-a.balance
      a.balance <- init
                                         a.balance <- (bal
      return a
                                     func (a *Account) Deposit(v int) {
                                         bal := <-a.balance
                                         a.balance <- (bal + v)
```

select statement in Go

 select allows a goroutine to wait on multiple channels at once

```
for {
    select {
        buySnacks(money)
        case money := <-mom:
        buySnacks(money)
        case default:
        starve()
        time.Sleep(5 * time.Second)
    }
}</pre>
```

Handle timeouts using select

```
func askServer(
    result chan int,
    timeout chan bool) {
         time.Sleep(5 * time.Second)
    // Ask server
    go func() {
     response := // ... send RPC
         result <- response
    }()
}
```

Handle timeouts using select

```
result := make(chan int)
timeout := make(chan bool)
// Asynchronously request an
// answer from server, timing
// out after X seconds
askServer(result, timeout)
// Wait on both channels
                                                 }()
select {
      case res := <-result;</pre>
               handleResult(res)
        case <-timeout:</pre>
                fmt.Println("Timeout!")
}
                                                 }()
                                            }
```

```
func askServer(
    result chan int,
    timeout chan bool) {

    // Start timer
    go func() {
        time.Sleep(5 * time.Second)
        timeout <- true
    }()

    // Ask server
    go func() {
        response := // ... send RPC
        result <- response
    }()</pre>
```